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Q_p -Continuous Multifunctions and Q_p – Closed Multifunctions

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ABSTRACT

In this paper, by means of Q_p -open and Q_p – closed sets, we introduce we have provided some basic definitions that we need in the research in addition to the definition of, Q_p –continuous multifunctions and investigate certain ramifications of Q_p –continuous multifunctions, along with their several properties, characterizations and mutual relationships. Further we introduce new types of multifunctions, called Q_p – O – closed multifunctions via Q_p –open sets. The relationship between these multifunctions and Q_p - continuous multifunction are studied .

MSC..

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1.Introduction

Continuity is an important concept to study and investigation of classical point set topology theory, generalization of this concept can be made by using weaker forms of open groups . In 1965, O. Njaste[11] introduced the concept and definition of α -open and α – closed sets in topology . In 1970 N. Levine[10] introduced and studied the notion of Generalized closed sets (g – closed) in topology . In 1982[2], gives the concept of term **pre – open and pre – closed** sets and studies its properties . In 1993 [5] introduced the notion of Generalized α -closed sets in topology ($g\alpha$ – closed set) . In the year 1994 [6], introduced and investigated the notion of αg – closed sets and αg – open sets by involving α – closed and g – closed sets. In 1996 [7], obtained a new class of sets in a topological space, known as gp – closed sets and pg – closed .

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In 2022 [8], introduced and study new class of sets is called Q_p – closed set and Q_p – open sets in a topological spaces. The theory of multivalued functions (multifunction) was first codified by ber. [13].

The aim of this paper is to a new form of continuous multivalued functions called Q_p –continuous multifunctions, and a new type of the multivalued functions called Q_p – O – closed multifunctions are introduced and studied by using Q_p – open and Q_p – closed sets.

2-Preliminaries and Definitions

Throughout the present paper, X, Z and Y are always topological spaces (short : TO.S). Let ω be a subset of a TO.S X , We denote the interior and the closure of a set ω by $mt(\omega)$ and $Cl(\omega)$, respectively. $O(X)$ is the of all open sets in TO.S X . $C(X)$ is the of all closed sets in TO.S X . the complement of a subset ω in X denoted by ω^c . By a topological multifunction $\Gamma : X \rightarrow Y$, it is meant a multifunction from a TO.S X to another TO.S Y . We will use the symbol \blacklozenge to indicate end of the proof.

Definition 2.1: Let X and Y be a TO.S :

- 1) The corresponding $\Gamma : X \rightarrow Y$ is called a multivalued function if given any $X \ni x$, then $\Gamma(x)$ will be a nonempty subset of Y [1].
- 2) Let $\Gamma : X \rightarrow Y$ be a multivalued and $X \supseteq \omega, Y \supseteq \upsilon$ then $\Gamma(\omega) = \cup \{ \Gamma(x) : \omega \ni x \}$ is called image of the set ω , $\Gamma^{+1}(\upsilon) = \{ X \ni x : \upsilon \supseteq \Gamma(x) \}$ is called the upper inverse of the set υ , $\Gamma^{-1}(\upsilon) = \{ X \ni x : \Gamma(x) \cap \upsilon \neq \emptyset \}$ is called the lower inverse of the set υ [13],

Remark 2.2[12] : Let $\Gamma : X \rightarrow Y$ be a multivalued function and $Y \supseteq \upsilon$, then $\Gamma^{+1}(\upsilon) = (\Gamma^{-1}(\upsilon))^c$ and $\Gamma^{-1}(\upsilon) = (\Gamma^{+1}(\upsilon))^c$.

Definition 2.3 : A subset ω of a TO.S X is called

- 1) Preclosed [preopen] set if $\omega \supseteq Cl(mt(\omega))$ [$\omega \subseteq mt(Cl(\omega))$] [2].
- 2) α – closed [α – open] set if $\omega \supseteq Cl(mt(Cl(\omega)))$ [$\omega \supseteq mt(Cl(mt(\omega)))$] [11].
- 3) g – closed set if $\upsilon \supset Cl(\omega)$ whenever $\upsilon \supset \omega$ and $O(X) \ni \upsilon$ and (ω^c) is g – open [10].
- 4) gp – closed set if $\omega \supseteq Cl_p(\omega)$ whenever $\upsilon \supset \omega$ and $O(X) \ni \upsilon$, where $Cl_p(\omega)$ perclosuer of ω (the intersection of all preclosed sets containing ω is called perclosure of ω) and (ω^c) is gp – open [7].

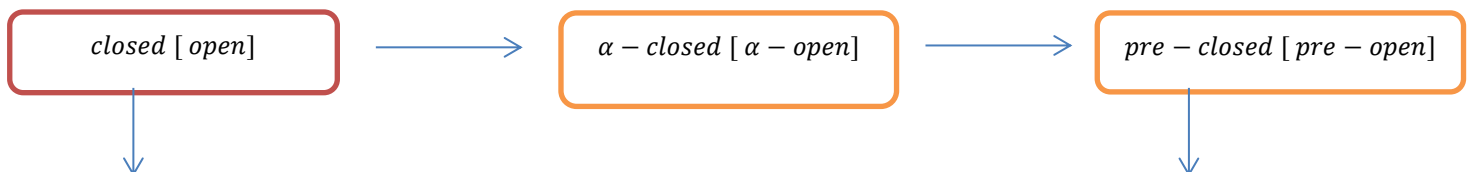
Definition 2.4[8]: A subset ω of a TO.S X is called Q_p – closed [Q_p – open] set if $\omega \supseteq Cl_{gp}(int(\omega))$, where $Cl_{gp}(int(\omega))$ is gp –closure of $int(\omega)$ [$\omega \subseteq int_{gp}(Cl(\omega))$], where $Cl_{gp}(int(\omega))$ gp interior of $Cl(\omega)$ [$Q_p C(X)$ [$Q_p O(X)$] is the set of all Q_p – closed [Q_p – open sets in a TO.S X .

Definition 2.5:

- 1) $Cl_{Q_p}(\omega)$ is called Q_p – closure of ω in a TO.S X if $Cl_{Q_p}(\omega) = \cap \{ \upsilon : \upsilon \supseteq \omega \text{ and } Q_p C(X) \ni \upsilon \}$ [8].
- 2) $mt_{Q_p}(\omega)$ is called Q_p – interior of ω in a TO.S X if $mt_{Q_p}(\omega) = \cup \{ \upsilon : \upsilon \subseteq \omega \text{ and } Q_p O(X) \ni \upsilon \}$ [8].
- 3) We say that a set υ of a TO.S X is a Q_p – neighborhood of a point x if υ contains a Q_p – open set to which x belongs.

Remark 2.6 [8]

The diagram below represents the relationship between the Q_p – closed type sets and the other closed sets :



g – closed [g – open]



Q_p – closed [Q_p – open]



gp – closed [gp – open]

Remark 2.7 [8]

- 1) In a TO.S X , arbitrary intersection of Q_p – closed sets is Q_p – closed set.
- 2) In a TO.S X , arbitrary union of Q_p – open sets is Q_p – open set.
- 3) In a TO.S X , union of two Q_p – closed sets need not Q_p – closed set.
- 4) In a TO.S X , intersection of two Q_p – open sets need not Q_p – open set.
- 5) If $Cl_{Q_p}(\omega) = \omega$, then $Q_p C(X) \ni \omega$.
- 6) If $mt_{Q_p}(\omega) = \omega$, then $Q_p O(X) \ni \omega$.

Definition 2.6

- 1) Let (D, \geq) be a directed set. A function $\chi : D \rightarrow X$ is called net in X , denoted by $(\chi_\alpha : D \ni \alpha)[1]$.
- 2) The net χ_α is eventually in ω if there exists $\alpha_0 \in I$ such that $\omega \ni \chi_\alpha$, for each $\alpha \geq \alpha_0$ [1].
- 3) The net χ_α in a TO.S X is called converges to a point x , if χ_α is eventually in every neighborhood of x [1].
- 4) The net χ_α in a TO.S X is called Q_p – converges to a point x , if χ_α is eventually in every Q_p – neighborhood of x .

Definition 2.7

- 1) A TO.S X is called Q_p – H space if for each two points $x_1 \neq x_2$ in X , there exist $Q_p O(X) \ni \nu_1, \nu_2$ such that $\nu_1 \ni x_1$, $\nu_2 \ni x_2$ and $\nu_1 \cap \nu_2 = \emptyset$.
- 2) A subset ω of a TO.S X is said to be Q_p – compact relative to TO.S X if every cover of ω by Q_p – open sets of X has a finite sub cover.
- 3) Let X be a TO.S, we say that X is Q_p – disconnected if it is the union of two non-empty Q_p – open sub sets, otherwise is Q_p – connected.

Definition 2.8 [12]: Let (D, \geq) be a directed set, $\{\Gamma_\alpha : D \ni \alpha\}$ be a net of multivalued function $\Gamma_\alpha : X \rightarrow Y$ and Γ a multivalued function on X into Y , $\{\Gamma_\alpha : D \ni \alpha\}$ is said to be

- 1) Upper pointwise convergent to Γ , if for each $X \ni x$ and each open set $Y \supseteq \omega$ containing $\Gamma(x)$, there exists $D \ni \beta$ such that $\Gamma_\alpha^{-1}(\omega) \ni x$ for each $\alpha \geq \beta$
- 2) Lower pointwise convergent to Γ , if for each $X \ni x$ and each open set $Y \supseteq \omega$ meeting $\Gamma(x)$, there exists $D \ni \beta$ such that $\Gamma_\alpha^{-1}(\omega) \ni x$ for each $\alpha \geq \beta$
- 3) Pointwise convergent if it is both upper pointwise convergent and lower pointwise convergent.

Definition 2.9 Let $\Gamma : X \rightarrow Y$ be a topological multifunction, then

- 1) Γ is called upper, (lower) continuous (short : U.C, L.C), at a point $X \ni x$, if for each open set ν in Y with $\nu \supseteq \Gamma(x)$ ($\Gamma(x) \cap \nu \neq \emptyset$) there exists open set ω containing x such that $\nu \supseteq \Gamma(\omega)$ ($\Gamma(z) \cap \nu \neq \emptyset$ for all $z \in \omega$), Γ is said to be U..C(L.C, if Γ is U.C(L.C) at each point $X \ni x$. Γ is called continuous, if it is U.C and L.C at each point $X \ni x$. [12]

- 2) Γ is called (upper – per (lower – per) continuous (short : $U.P.C, L.P.C$)), at a point $X \ni x$, if for each open set ν in Y with $\nu \supseteq \Gamma(x)$ ($\Gamma(x) \cap \nu \neq \emptyset$) there exists per – open set ω containing x such that $\nu \supseteq \Gamma(\omega)$ ($\Gamma(z) \cap \nu \neq \emptyset$ for all $z \in \omega$), Γ is said to be $U.P.C(L.P.C)$, if Γ is $U.P.C(L.P.C)$ at each point $X \ni x$. Γ is called per – continuous, if it is $U.P.C$ and $L.P.C$ at each point $X \ni x$. [13]
- 3) Γ is called (upper – α (lower – α) continuous (short : $U.\alpha.C, L.\alpha.C$)), at a point $X \ni x$, if for each open set ν in Y with $\nu \supseteq \Gamma(x)$ ($\Gamma(x) \cap \nu \neq \emptyset$) there exists α – open set ω containing x such that $\nu \supseteq \Gamma(\omega)$ ($\Gamma(z) \cap \nu \neq \emptyset$ for all $z \in \omega$), Γ is said to be $U.\alpha.C(L.\alpha.C)$, if Γ is $U.\alpha.C(L.\alpha.C)$ at each point $X \ni x$. Γ is called α – continuous, if it is $U.\alpha.C$ and $L.\alpha.C$ at each point $X \ni x$. [14]
- 4) Γ is called surjection if for each $Y \ni y$ there exists an element $X \ni x$ such that $\Gamma(x) \ni y$. [9]
- 5) Γ is called point closed (connected, compact) if for each $X \ni x$, $\Gamma(x)$ is closed (connected, compact) in Y . [3]

3. Q_p – continuous multifunctions

In the following section, the new concept of α – continuous multifunctions, introduced and studied and several characterization and properties of these forms are proved .

Definition 3.1 Let $\Gamma : X \rightarrow Y$ be a topological multifunction ; then

- 1) Upper Q_p – continuous ($U.Q_p.C$) at a point $X \ni x$, if for each open set ν in Y with $\Gamma(x) \supseteq \nu$ there exists $Q_p O(X) \ni \omega$ containing x such that $\nu \supseteq \Gamma(\omega)$. Γ is said to be $U.Q_p.C$, if Γ is $U.Q_p.C$ at each point $X \ni x$.
- 2) Lower Q_p – continuous ($L.Q_p.C$) at a point $X \ni x$, if for each open set ν in Y with $\Gamma(x) \cap \nu \neq \emptyset$ there exists $Q_p O(X) \ni \omega$ containing x such that $\Gamma(z) \cap \nu \neq \emptyset$ for all $z \in \omega$. Γ is said to be $L.Q_p.C$, if Γ is $L.Q_p.C$ at each point $X \ni x$.
- 3) Q_p – continuous ($Q_p.C$) at a point $X \ni x$, if it is both ($U.Q_p.C$) and ($L.Q_p.C$) at x . Γ is called $Q_p.C$, if it is $Q_p.C$ at each point $X \ni x$.

Example 3.2 : Let $X = \{e_1, e_2\}, T_X = \{X, \emptyset, \{e_1\}, \{e_2\}\}$ be a TO.S on X . $Y = \{h_1, h_2, h_3\}, T_Y = \{Y, \emptyset, \{h_1\}, \{h_2, h_3\}\}$ be a TO.S on Y . A multifunction $\Gamma : X \rightarrow Y$ defines by Γ by $\Gamma(e_1) = h_1$, and $\Gamma(e_2) = \{h_2, h_3\}$. Γ is $U.Q_p.C$ and $L.Q_p.C$.

Theorem 3.3 Let $\Gamma : X \rightarrow Y$ be a topological multifunction ; then the following statements are equivalent :

- 1) Γ is $L.Q_p.C$.
- 2) $Q_p O(X) \ni \Gamma^{-1}(\nu)$, for each open set ν in a TO.S Y .
- 3) $Q_p C(X) \ni \Gamma^{+1}(\kappa)$, for each closed set κ in a TO.S Y .
- 4) $Cl(\Gamma(\omega)) \supseteq \Gamma(Cl_{Q_p}(\omega))$, for each set ω in a TO.S X
- 5) $\Gamma^{+1}(Cl(\beta)) \supseteq Cl_{Q_p}(\Gamma^{+1}(\beta))$, for each set β in a TO.S Y .
- 6) $mt_{Q_p}(\Gamma^{-1}(\beta)) \supseteq \Gamma^{-1}(mt(\beta))$, for each set β in a TO.S Y .
- 7) For each $X \ni x$ and for each open set ν in a TO.S Y such that $\Gamma(x) \cap \nu \neq \emptyset$, there exists a Q_p – neighborhood ω of x such that if $\omega \ni u$; then $\Gamma(u) \cap \nu \neq \emptyset$.
- 8) For each $X \ni x$ and for each net χ_α which Q_p – converges to x in X and for each open set ν in Y , such that $\Gamma^{-1}(\nu) \ni x$; then the net χ_α is eventually in $\Gamma^{-1}(\nu)$.

Proof : 1) \Rightarrow 2) Let $\Gamma^{-1}(\nu) \ni x$ in a TO.S X , ν any open subset of Y of a TO.S Y , from 1) we get there exists $Q_p O(X) \ni \omega$ such that $\Gamma^{-1}(\nu) \supseteq \omega \ni x$; therefore, $Q_p O(X) \ni \Gamma^{-1}(\nu)$.

2)⇒3) Let κ be a closed set in a TO.S Y ; then κ^c is open set in Y from 2) we obtain $Q_p \mathcal{O}(X) \ni I^{-1}(\kappa^c)$, since $Q_p \mathcal{O}(X) \ni I^{-1}(\kappa^c) = (I^{-1}(\kappa))^c$; then $Q_p \mathcal{C}(X) \ni I^{-1}(\kappa)$.

3) ⇒4) Let $X \ni \omega$; then $\Gamma(\omega)$ is subset of a TO.S Y and $Cl(\Gamma(\omega))$ is closed set in Y . since Γ is L. $Q_p.C$; then $Q_p \mathcal{C}(X) \ni I^{-1}(Cl(\Gamma(\omega)))$, in view fact that $Cl(\Gamma(\omega)) \supseteq \Gamma(\omega)$ implies that to $I^{-1}(Cl(\Gamma(\omega))) \supseteq \omega$, It follows that $Cl_{Q_p}(I^{-1}(Cl(\Gamma(\omega)))) \supseteq Cl_{Q_p}(\omega)$; therefore , $Cl(\Gamma(\omega)) \supseteq \Gamma(Cl_{Q_p}(I^{-1}(Cl(\Gamma(\omega)))) \supseteq \Gamma(Cl_{Q_p}(\omega))$.

4) ⇒5) Let $Y \ni \beta$, then $Q_p \mathcal{C}(X) \ni Cl_{Q_p}(I^{-1}(\beta))$, from this we get $I^{-1}(\beta) \supseteq Cl_{Q_p}(I^{-1}(\beta))$, then $(\Gamma(I^{-1}(\beta))) \supseteq \Gamma(Cl_{Q_p}(I^{-1}(\beta)))$ and $Cl(\beta) \supseteq Cl(\Gamma(I^{-1}(\beta)))$, this implies $I^{-1}(Cl(\beta)) \supseteq I^{-1}(Cl(\Gamma(I^{-1}(\beta)))) \supseteq Cl_{Q_p}(I^{-1}(\beta))$.

5)⇒6) let β any set of a TO.S Y , then $Q_p \mathcal{O}(X) \ni mt_{Q_p}(I^{-1}(\beta))$ and $Q_p \mathcal{C}(X) \ni (mt_{Q_p}(I^{-1}(\beta)))^c = Cl_{Q_p}(I^{-1}(\beta))^c = Cl_{Q_p}(I^{-1}(\beta^c))$

Then $(I^{-1}Cl(\beta^c)) \supseteq Cl_{Q_p}(I^{-1}(\beta^c))$ and $(I^{-1}Cl(\beta^c)) = I^{-1}((mt\beta)^c) = (I^{-1}(mt\beta))^c$ from this we get $mt_{Q_p}(I^{-1}(\beta)) \supseteq I^{-1}(mt(\beta))$.

6)⇒7) Let $X \ni x$ and v be any open set in a TO.S Y , such that $\Gamma(x) \cap v \neq \phi$, then $mt_{Q_p}(I^{-1}(v)) \supseteq I^{-1}(mt(v))$, and $mt_{Q_p}(I^{-1}(v)) \supseteq I^{-1}(v)$. It follows that $Q_p \mathcal{O}(X) \ni I^{-1}(v)$, we take $\omega = I^{-1}(v)$ is Q_p - neighborhood, then for each $\omega \ni u$, $\Gamma(u) \cap v \neq \phi$.

7)⇒8) Let $X \ni x$ and let a net χ_α which Q_p - converges to x in a TO.S X , v any open set in a TO.S Y , such that $I^{-1}(v) \ni x$ from 7) there exists $Q_p \mathcal{O}(X) \ni \omega$ and containing x , $\Gamma(u) \cap v \neq \phi$ for each $\omega \ni u$, then $\omega = I^{-1}(v)$, since χ_α is Q_p - converges to x in a TO.S X , then χ_α is eventually in every Q_p - neighborhood of a point x , therefore , the net χ_α is eventually in $I^{-1}(v)$.

8)⇒1) Suppose that 1) is not true , there exists a point $X \ni x$ and v an open set in a TO.S Y with $I^{-1}(v) \ni x$ such that for set $Q_p \mathcal{O}(X) \ni \omega$ containing x , $I^{-1}(v) \not\supseteq \omega$. Let $\omega \ni \chi_\omega$ and $I^{-1}(v) \not\supseteq \chi_\omega$ for each $Q_p \mathcal{O}(X) \ni \omega$ and containing x , therefore , the net χ_ω Q_p - converges to a point x , but χ_ω is not eventually in $I^{-1}(v)$. This is contradiction , hence Γ is L. $Q_p.C$. ♦

Theorem 3.4 Let $\Gamma : X \rightarrow Y$ be a topological multifunction ; then the following statements are equivalent :

- 1) Γ is U. $Q_p.C$.
- 2) $Q_p \mathcal{O}(X) \ni I^{-1}(v)$, for each open set v in a TO.S Y .
- 3) $Q_p \mathcal{C}(X) \ni I^{-1}(\kappa)$, for each closed set κ in a TO.S Y .
- 4) $I^{-1}(Cl(\beta)) \supseteq Cl_{Q_p}(I^{-1}(\beta))$, for each set β in a TO.S Y .
- 5) $mt_{Q_p}(I^{-1}(\beta)) \supseteq I^{-1}(mt(\beta))$, for each set β in a TO.S Y .
- 6) For each $X \ni x$ and for each open set v in a TO.S Y such that $v \supseteq \Gamma(x)$, there exists a Q_p - neighborhood ω of x such that if $\omega \ni u$; then $v \supseteq \Gamma(u)$.
- 7) For each $X \ni x$ and for each net χ_α which Q_p - converges to x in X and for each open set v in Y , such that $I^{-1}(v) \ni x$; then the net χ_α is eventually in $I^{-1}(v)$.

Proof: The details of the proof are similar to the details in the previous theorem . ♦

Remark 3.5 The following implication are hold

- 1) Γ is L.C $\Rightarrow \Gamma$ is L. $\alpha.C \Rightarrow \Gamma$ is L.P.C $\Rightarrow \Gamma$ is L. $Q_p.C$
- 2) Γ is U.C $\Rightarrow \Gamma$ is U. $\alpha.C \Rightarrow \Gamma$ is U.P.C $\Rightarrow \Gamma$ is U. $Q_p.C$.

While the converses are not true in general as the following

Example 3.6: Let $\Gamma : (X, T_X) \rightarrow (Y, T_Y)$ be a topological multifunction, where $X = \{e_1, e_2, e_3\}$, $T_X = \{X, \phi, \{e_1\}\}$ and $Y = \{h_1, h_2, h_3\}$, $T_Y = \{Y, \phi, \{h_3\}, \{h_1, h_2\}\}$. Define Γ by $\Gamma(e_1) = \Gamma(e_2) = h_1$, and $\Gamma(e_3) = h_3$, then $\{h_3\}$ an open set in a TO.S Y and $\Gamma^{-1}(h_3) = \{e_3\} \in Q_p O(X)$ but $\{e_3\}$ is not per – open set in a TO.S X, therefore Γ is U. Q_p. C but Γ is not U. P. C

Theorem 3.7 Let $\Gamma : X \rightarrow Y$ be a topological multifunction, if Γ is U. Q_p. C, then $G : X \rightarrow \Gamma(X)$ is also U. Q_p. C where $G(x) = \Gamma(x)$.

Proof: Let v any open set in a TO.S Y, then $\Gamma(X) \cap v$ is open set in a space $\Gamma(X)$, $G^{-1}(\Gamma(X) \cap v) = X \cap G^{-1}(v) = \Gamma^{-1}(v)$, since Γ is U. Q_p. C, then $Q_p O(X) \ni \Gamma^{-1}(v)$, therefore, G is U. Q_p. C. ♦

Theorem 3.8 Let $\{\Gamma_\ell : X \rightarrow Y, D \ni \ell, D \text{ index}\}$ be a net of U. Q_p. C (L. Q_p. C) topological multifunctions, Γ_ℓ be an upper (lower) pointwise convergent to $\Gamma : X \rightarrow Y$ and Γ is point closed, if Y is normal (regular) and for each open set \mathcal{M} of Y with $\Gamma^{-1}(\mathcal{M}) \neq \phi$ ($\Gamma^{-1}(\mathcal{M}) \neq \phi$) and $D \ni \mathcal{J}$, there exists $\mathcal{J} \leq \mathcal{L}$ such that $\Gamma_\ell(x) \cap \mathcal{M} \neq \phi$ ($\mathcal{M} \ni \Gamma_\ell(x)$), for all $\Gamma^{-1}(\mathcal{M}) \ni x$ ($\Gamma^{-1}(\mathcal{M}) \ni x$), then Γ is also U. Q_p. C (L. Q_p. C).

Proof: Suppose Γ is not U. Q_p. C at a point ε in X ; then there exists an open set v in Y containing $\Gamma(\varepsilon)$ such that for Q_p – open set ω in X containing ε , there exists $\omega \ni \varepsilon_0$ and $v \not\supseteq \Gamma(\varepsilon_0)$, that's mean $\Gamma(\varepsilon_0) \cap v^c \neq \phi$, by the assumption Y is normal and $Y \ni \Gamma(\varepsilon)$, $\Gamma(\varepsilon)$ closed and $v \supseteq \Gamma(\varepsilon)$, there exists an open set e such that $v \supseteq Cl(e) \ni e \ni \Gamma(\varepsilon)$, let's say $\mathcal{M} = Y - Cl(e)$, then $\mathcal{M} \ni v^c$. Where $\{\Gamma_\ell : X \rightarrow Y, D \ni \ell\}$ is upper pointwise convergent to Γ at ε . that's mean there exists $D \ni \mathcal{J}$ whereas $\Gamma_\ell(\varepsilon) \subseteq e$, for each $\mathcal{J} \leq \ell$, where $\Gamma(\varepsilon_0) \cap v^c \neq \phi$, and then $\Gamma(\varepsilon_0) \cap \mathcal{M} \neq \phi$ implies that $\phi \neq \Gamma^{-1}(\mathcal{M}) \ni \varepsilon_0$. subsequently there exists $\mathcal{J} \leq \mathcal{L}$ whereas $\phi \neq \mathcal{M} \cap \Gamma_\ell(x)$, for all $\Gamma^{-1}(\mathcal{M}) \ni x$, implies that $\phi \neq \mathcal{M} \cap \Gamma_\ell(\varepsilon_0)$, therefore $e \not\supseteq \Gamma(\varepsilon_0)$, whereas Γ_ℓ is not U. Q_p. C at ε , this contradiction; therefore, Γ is U. Q_p. C.

With the same details, it can be shown that Γ is L. Q_p. C

Theorem 3.9 Let $\Gamma : X \rightarrow Y$ be an U. Q_p. C topological multifunction and point compact, if Y is Hausdorff – space and $\Gamma(x_1) \cap \Gamma(x_2) = \phi$, for all $x_1 \neq x_2$ in a TO.S X, then X is Q_p – H space.

Proof: Let x_j, x_ℓ be any points of X such that $x_j \neq x_\ell$, since $\Gamma(x_j), \Gamma(x_\ell)$ are compact sets, $\Gamma(x_j) \cap \Gamma(x_\ell) = \phi$ in a TO.S Y and Y is a Hausdorff space, there exist two open sets v_j containing $\Gamma(x_j)$ and v_ℓ containing $\Gamma(x_\ell)$ and $v_j \cap v_\ell = \phi$. Since Γ is U. Q_p. C, then $Q_p O(X) \ni \Gamma^{-1}(v_j), \Gamma^{-1}(v_\ell)$ and $\Gamma^{-1}(v_j) \ni x_j, \Gamma^{-1}(v_\ell) \ni x_\ell$ such that $\Gamma^{-1}(v_j) \cap \Gamma^{-1}(v_\ell) = \Gamma^{-1}(v_j \cap v_\ell) = \Gamma^{-1}(\phi) = \phi$. By definition (2.7(1)) X is Q_p – H space. ♦

4. Q_p – O – Closed Multifunctions

In this section, the new concept of Q_p – O – closed multifunctions, introduced and studied, and several properties of these new concept are proved.

Definition 4.1 A topological multifunction $\Gamma : X \rightarrow Y$ is said to be Q_p – O – Closed if for each $X \ni x$ and $Y \ni y$, for which $\Gamma(x) \not\ni y$, there exists $Q_p O(X) \ni \omega$ containing x and open set v in a TO.S Y containing y , such that $\Gamma(x_0) \cap v = \phi$, for each $\omega \ni x_0$.

Example 3.6: Let $X = \{e_1, e_2, e_3\}$, $T_X = \{X, \phi, \{e_1\}, \{e_3\}, \{e_1, e_3\}, \{e_2, e_3\}\}$ be a TO.S on X . $Y = \{h_1, h_2, h_3\}$, T_Y is a discrete, TO.S on Y . A multifunction $\Gamma : X \rightarrow Y$ defines by Γ by $\Gamma(e_1) = \{h_1\}$, $\Gamma(e_2) = \{h_1, h_2\}$ and $\Gamma(e_3) = \{h_2\}$. Γ is Q_p – O – Closed. but Γ is not Q_p – Continuous

The following theorem give the relationships between the concept Q_p – continuous multifunctions and Q_p – O – Closed multifunction.

Theorem 4.2 Let $\Gamma : X \rightarrow Y$ be a multifunction from a TO.S X into a Hausdorff TO.S Y, if Γ is U. Q_p. C and point compact, then Γ is Q_p – O – Closed.

Proof: Suppose $\Gamma : X \rightarrow Y$ is U. Q_p. C on a TO.S X and $\Gamma(x) \not\ni y$, since $\Gamma(x)$ is compact and Y is Hausdorff TO.S, then there exist disjoint two open set v_1 and v_2 in a TO.S Y such that $v_1 \ni y$ and $v_2 \supseteq \Gamma(x)$. Since Γ is U. Q_p. C, there exists $Q_p O(X) \ni \omega$ such that $\omega \ni x$ implies $v_2 \supseteq \Gamma(\omega)$, then $\Gamma(\omega) \cap v_1 = \phi$. It follows that Γ is Q_p – O – closed. ♦

Theorem 4.3 If $\Gamma : X \rightarrow Y$ is a Q_p – O – Closed multifunction, then $\Gamma(e)$ is closed subset of a TO.S Y, for each $e \in Q_p$ – Compact relative to a TO.S X.

Proof: Assume $\Gamma(e) \not\ni y$, then for each $e \ni x$, $\Gamma(x) \not\ni y$. By definition (4.1) there exist $Q_p O(X) \ni \omega_x$ containing x and an open set v_x containing y such that $\Gamma(\omega_x) \cap v_x = \phi$. The family $\{\omega_x : e \ni x\}$ is a cover of a set e and $Q_p O(X) \ni \omega_x$ for each x , since e is Q_p – Compact

there exists a finite subset \mathcal{M} of \mathcal{E} such that $\cup \{\omega_x : \mathcal{M} \ni x\} \supseteq \mathcal{E}$. Take $\nu = \{\nu_x : \mathcal{M} \ni x\}$, then ν is an open set containing element y and $\Gamma(\mathcal{E}) \cap \nu = \phi$, this means that $\Gamma(\mathcal{E})^c \supseteq \nu$, therefore, $\Gamma(\mathcal{E})$ is closed in a TO.SY. ♦

Definition 4.4 A topological multifunction $\Gamma : X \rightarrow Y$ is called contra Q_p – open if the image of every Q_p – open set in a TO.SX is closed set in a TO.SY.

Theorem 4.5 If $\Gamma : X \rightarrow Y$ is contra Q_p – open multifunction such that the inverse image for each point of a TO.SY is Q_p – Closed set in a TO.SX, then Γ is Q_p – O – Closed .

Proof: Let $\Gamma(x) \ni y$, then $\Gamma^{-1}(y) \ni x$, since $\Gamma^{-1}(y)$ Q_p – Closed, then there exists ν Q_p – open set containing x such that $\nu \cap \Gamma^{-1}(y) = \phi$. Since Γ is contra Q_p – open, then $\Gamma(\nu)$ is closed set in a TO.SY, this implies that there exists an open set \mathcal{M} in a TO.SY such that $\mathcal{M} \ni y$ and $\Gamma(\nu) \cap \mathcal{M} = \phi$. Hence Γ is Q_p – O – Closed . ♦

Theorem 4.6 If $\{\Gamma_\ell : X \rightarrow Y, \ell \in I\}$ is a family of Q_p – O – Closed multifunction from a TO.SX into a TO.SY, then $\Gamma(x) = \cap_{\ell \in I} \Gamma_\ell(x)$ is Q_p – O – Closed, $\Gamma(x) = \cap_{\ell \in I} \Gamma_\ell(x)$.

Proof: let $\Gamma(x_1) \ni y_1$, then there exists $\ell_1 \in I$ such that $\Gamma_{\ell_1}(x_1) \ni y_1$, since Γ_{ℓ_1} is Q_p – Closed, then there exists $Q_p \mathcal{O}(X) \ni \nu$ containing x_1 and ω open set in TO.SY containing y_1 such that $\Gamma_{\ell_1}(\nu) \cap \omega = \phi$, from this we obtain $\Gamma(\nu) \cap \omega = \phi$, therefore, Γ is Q_p – O – Closed . ♦

Theorem 4.7 If $\Gamma : X \rightarrow Y$ is Q_p – O – Closed topological multifunction, then $\Gamma^{-1}(\nu)$ is Q_p – Closed, for each ν compact set in a TO.SY.

Proof: Let ν be arbitrary compact set in a TO.SY and $\Gamma^{-1}(\nu) \ni x$, $\Gamma^{-1}(\nu) = \{x : \Gamma(x) \cap \nu \neq \phi\}$, then $\Gamma^{-1}(\nu) \ni x$, for each $\nu \in \mathcal{E}$. Since Γ is Q_p – Closed, there exist $Q_p \mathcal{O}(X) \ni \mathcal{M}_{x_\ell}$ and open set \mathcal{M}_ℓ such that $\mathcal{M}_{x_\ell} \ni x$ and $\mathcal{M}_\ell \ni \ell$ implies $\Gamma(\mathcal{M}_{x_\ell}) \cap \mathcal{M}_\ell = \phi$. The family $\{\mathcal{M}_\ell : \nu \ni \ell\}$ is open cover of ν , since ν is compact, then there exists $\{\mathcal{M}_{\ell_1}, \mathcal{M}_{\ell_2}, \mathcal{M}_{\ell_3}, \dots, \mathcal{M}_{\ell_n}\}$ is finite sub cover such that $\cup_{i=1}^n \mathcal{M}_{\ell_i} \supseteq \nu$, let $\mathcal{M}_x = \cap_{i=1}^n \mathcal{M}_{x_{\ell_i}}$ such that $\mathcal{M}_x \ni x$. If $\mathcal{M}_x \cap \Gamma^{-1}(\nu) = \phi$, then $\Gamma^{-1}(\nu)$ is Q_p – Closed. Now, for showing this, suppose $\mathcal{M}_x \cap \Gamma^{-1}(\nu) \neq \phi$, there exists $\mathcal{M}_x \ni x_0$ and $\Gamma^{-1}(\nu) \ni x_0$ then $\mathcal{M}_{x_{\ell_i}} \ni x_0$, for each $i = 1, 2, \dots, n$ and $\Gamma(x_0) \cap \nu \neq \phi$, this implies there exists $\Gamma(x_0) \ni y$ and $\nu \ni y$, since $\cup_{i=1}^n \mathcal{M}_{\ell_i} \supseteq \nu$, then $\mathcal{M}_{\ell_i} \ni y$ where $i = j$, there exists $\mathcal{M}_{x_{\ell_j}}$ such that $\Gamma(\mathcal{M}_{x_{\ell_j}}) \cap \mathcal{M}_{\ell_j} \neq \phi$, this is contradiction, therefore $\mathcal{M}_x \cap \Gamma^{-1}(\nu) = \phi$ and $\Gamma^{-1}(\nu)$ is Q_p – Closed set in X . ♦

Now, the following theorem is study the converse of theorem 4.2 .

Corollary 4.8 If $\Gamma : X \rightarrow Y$ is Q_p – O – Closed topological multifunction and Y is a compact a TO.S, then Γ is U. Q_p . C.

Proof: Let $\Gamma : X \rightarrow Y$ be Q_p – Closed and ν be any closed subset of a TO.S, since Y is a compact space, then ν is compact set in Y , from theorem (4.7) we get $\Gamma^{-1}(\nu)$ is Q_p – Closed, this implies Γ is U. Q_p . C . ♦

5-Conclusion

Concepts of openness and continuity is the basic concepts of study and survey of topological spaces. In this work, we introduced some new concepts of a kind of continuous multifunctional functions called Q_p – Continuous multifunctions and studied its properties and it turned out to be an expansion of the space of continuous multifunctional and we have obtained some theorems that can be generalized to this type of continuity. This work is extended to Q_p – closed multifunctions and the relationships between Q_p – Continuous and Q_p – closed multifunctions are explored.

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