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Some Separation Axioms Via D-Set in Bitopological Space

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ARTICLEINFO	ABSTRACT
Article history: Received: 12 /1/2024 Rrevised form: 4 /2/2024 Accepted: 3 /3/2024 Available online: 30 /3/2024	In this paper, notions of some separation axioms by using D-set in bitopological space. We studied some of the fundamental properties and relations among types of D_k -bitopological spaces where k =0,1.
Keywords:	MSC
D-set, D_k -bitopological spaces, pairwise D_k -bitopological spaces and weak pairwise D_k -bitopological spaces for $k = 0, 1$.	

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1. Introduction:

Kelly In 1963 [3] defined bitopological spac . In 1966[4] Murdeshwar studied the concepts of pairwise- T_o and weak pairwise T_o spaces. In [5] 1982 Tong introduced definition of D-set . Tallafha In [1] studied continuous and pairwise continuous functions of bitopological spaces. In [6] O.Ravi investigated open set in bitopological space . Rupaya in [7] presented defined T_o -bitopological space . In [2] Khadiga investigated defined subbitopological spaces. In this paper we introduce and study the definition of D-set in bitopological space and some types of D_k –bitopological spaces for k=0,1.

2. D-set in bitopological space

Definition (2.1)[5]

Let (X, τ) is topological space .The subset H of X is said to be difference set (D-set) if there exist two open sets M and N in X such that M \neq X, H= M - N.

Definition (2.2)[3]

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If X non-empty set and σ_1 , σ_2 are two Topologies on X. A space (X, σ_1 , σ_2) is called bitopological space.

Definition (2.3)[6]

In bitopological space (X , σ_1 , σ_2) the subset K is said to be $\sigma_1\sigma_2$ -open set if K= U \cup V where U \in σ_1 and V \in σ_2 . The complement of $\sigma_1\sigma_2$ -open is called $\sigma_1\sigma_2$ -closed .

Definition (2.4)

A subset W of bitopological space (X, σ_1, σ_2) is called $\sigma_1 \sigma_2$ -difference set $(\sigma_1 \sigma_2 - D - set)$ if $W = U_1 \cup U_2$ where U_1 is D-set in (X, σ_1) and U_2 is D-set in (X, σ_2) .

Remark (2.1)

Every $\sigma_1 \sigma_2$ -open (is not equal to X) is $\sigma_1 \sigma_2$ -D-set.

But the converse is not true for example

Example (2.1)

Let X={h₁, h₂, h₃, h₄} and σ_1 ={ \emptyset , X,{h₁, h₂, h₃}, {h₂, h₃}}, σ_2 ={ \emptyset , X,{h₂,h₄}, {h₄}} are two topologies on X . Since A={h₁, h₂}={h₁} \cup {h₂}. Since {h₁} \notin σ_1 and {h₂} \notin σ_2 hence {h₁, h₂} is not $\sigma_1\sigma_2$ -open . But {h₁} is σ_1 -D- set and {h₂} is σ_2 -D- set then A is $\sigma_1\sigma_2$ -D- set

Definition (2.5)[1]

Afunction f: $(X, \sigma_1, \sigma_2) \rightarrow (Y, \rho_1, \rho_2)$ is called continuous if f: $(X, \sigma_1) \rightarrow (Y, \rho_1)$ and f: $(X, \sigma_2) \rightarrow (Y, \rho_2)$ are continuous where (X, σ_1, σ_2) and (Y, ρ_1, ρ_2) be two bitopological spaces

Theorem (2.1)

If $f:(X,\sigma_1,\sigma_2) \to (Y,\rho_1,\rho_2)$ is continuous therefore the inverse image of $\rho_1\rho_2$ -D-set is $\sigma_1\sigma_2$ -D-set.

Proof

Suppose G is $\rho_1\rho_2$ -D-set in Y .Then G =AUB suchthat A is ρ_1 -D-set and B is ρ_2 -D-sets in Y thus A=U-V and B=O-S where U,V \neq Y and (U,V \in ρ_1) and (0,S \in ρ_2) .Since f:(X, σ_1,σ_2) \rightarrow (Y, ρ_1,ρ_2) is continuous hence f:(X, σ_1) \rightarrow (Y, ρ_1) and f:(X, σ_2) \rightarrow (Y, ρ_2) are continuous . Thus f^{-1} (U), f^{-1} (0) \in σ_1 and f^{-1} (U), f^{-1} (V) \in σ_2 . And f^{-1} (U), f^{-1} (O) \neq X. Therefore f^{-1} (U) $-f^{-1}$ (V)= f^{-1} (U -V) = f^{-1} (A) hence f^{-1} (A) is σ_1 -D-set and f^{-1} (O) $-f^{-1}$ (C) = f^{-1} (D) is σ_2 -D-set in X. Thus the inverse image of $\rho_1\rho_2$ -D-set is $\sigma_1\sigma_2$ -D-set

3. D_{ν} -bitopological spaces

Definition (3.1)[7]

Bitopological space (X, σ_1, σ_2) is said to be T_o if and only if for each different points in X there exists U is $\sigma_1 \sigma_2$ -open set containing one not containing other.

Definition (3.2)

A bitopological space (X, σ_1, σ_2) is called D_o if and only if for each different points in X there exists $\sigma_1 \sigma_2$ -D- set containing one but not containing other .

Theorem (3.1)

Every T_o bitopological space is D_o .

Proof:

Let (X, σ_1, σ_2) is T_o and x, y in X such that $x \neq y$. Then there exist A is $\sigma_1 \sigma_2$ -open set such that $x \in A$, $y \notin A$. Thus A is $\sigma_1 \sigma_2$ -D-set we have (X, σ_1, σ_2) is D_o

Theorem (3.2)

If (X, σ_1) and (X, σ_2) is D_0 then (X, σ_1, σ_2) is D_0 .

Proof :

Suppose $x \neq y$ in X. Thus $\exists G_1 = \{x \in G_1, y \notin G_1\}$ is σ_1 -D-set in (X, σ_1) and $G_2 = \{x \notin G_2, y \in G_2\}$ is σ_2 -D-set in (X, σ_2) because (X, σ_1) and (X, σ_2) are D_o . Let $G = G_1 \cup G_2$ then $x \in G$ and $y \notin G$ then (X, σ_1, σ_2) is D_o .

Example (3.1)

Suppose X={ m , n , o , p } , σ_1 ={ \emptyset , X ,{m , o },{o}} and σ_2 = { \emptyset , X , {n , p},{p} . It is clear that (X , σ_1 , σ_2) is D_o . But $n \neq p$ and there is no σ_1 -D-set containing n not containing p thus (X, σ_1) is not D_o . And m \neq o and there is no σ_2 -D-set containing 1 not 3 thus (X , σ_2) is not D_o .

Theorem (3.3)

If f: $(M, \sigma_1, \sigma_2) \rightarrow (N, \rho_1, \rho_2)$ is continuous and one to one and N is D_0 -space then M D_0 -space.

Proof:

Let N is D_o and $x \neq y$ in M . Then there exist a, b in Y and $a \neq b$, (f(x)=a, f(y)=b). Since f is one to one hence $f(x) \neq f(y)$. Since Y is D_o then there exist U is $\rho_1 \rho_2$ -D-set in N such that $a \in U$ and b $\mathbb D$ U. we have the inverse image of U is $\sigma_1 \sigma_2$ -D-set in M containing x not y. Therefore (M, σ_1 , σ_2) is D_o .

Definition(3.3)[2]

For a bitopological space (Y,σ_1,σ_2) and $A \subseteq X$. $(A,\sigma_{1_A},\sigma_{2_A})$ is said to be subspace of (Y,σ_1,σ_2) when $\sigma_{1_A} = \{U_1 \cap A : U_1 \in \sigma_1\}$ and $\sigma_{2_A} = \{U_2 \cap A : U_2 \in \sigma_2\}$.

Theorem(3.4)

If (Y,σ_1,σ_2) is D_o and A subset of X then $(A,\sigma_{1_A},\sigma_{2_A})$ is D_o

Proof

Suppose a and b are two distance points in A thus a and b in Y. Since Y is D_o then there exist G is $\sigma_1\sigma_2$ -D-set in Y and G containing a not b. Hence $G = V_1 \cup V_2$ where V_1 is σ_1 -D-set and V_2 is σ_2 -D-set in Y. Then $V_1 = O_1 - S_1$ and $V_2 = O_2 - S_2$ such that $(O_1, S_1 \in \sigma_1)$, $(O_2, S_2 \in \sigma_2)$ and $(O_1, O_2 \neq Y)$.

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\begin{array}{l} \mathsf{A} \cap \mathsf{G} = \mathsf{A} \cap \left[ \; (O_1 - S_1) \cup (\; O_2 - S_2) \right] \\ = \left[ \; (\mathsf{A} \cap O_1) - (\mathsf{A} \cap S_1) \; \right] \cup \left[ \; (\mathsf{A} \cap O_2) - (\mathsf{A} \cap S_2) \; \right] \\ \mathsf{Since} \; (\mathsf{A} \cap O_1) \; , \; (\mathsf{A} \cap S_1) \in \sigma_{1_A} \; \; \mathsf{and} \; \left( \; \mathsf{A} \cap O_1 \; \right) \neq \mathsf{Y} \\ \qquad \qquad (\mathsf{A} \cap O_2) \; , \; (\mathsf{A} \cap S_2) \in \sigma_{2_A} \; \; \mathsf{and} \; \left( \; \mathsf{A} \cap O_2 \; \right) \neq \mathsf{Y} \\ \mathsf{Let} \; O_1^* - S_1^* = (\mathsf{A} \cap O_1) - (\mathsf{A} \cap S_1) \; \; \mathsf{and} \; O_2^* - S_2^* = (\mathsf{A} \cap O_2) - (\mathsf{A} \cap S_2) \\ \mathsf{Hence} \; O_1^* - S_1^* \; \; \mathsf{is} \; \; \sigma_{1_A} \text{-D-set} \; \mathsf{and} \; A_2^* = O_2^* - S_2^* \; \; \mathsf{is} \; \sigma_{2_A} \text{-D-set} \; \mathsf{in} \; \mathsf{A} \end{array}
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Then $A \cap G = A^* = A_1^* \cup A_2^*$ is $\tau_A \sigma_A$ -D-set in A . Since $x \in G$, $x \in A$ thus $x \in A^*$ and $y \notin G$, $y \in A$ thus $y \boxtimes A^*$. we have hence $(A, \sigma_{1_A}, \sigma_{2_A})$ is D_o .

The following example shows that converse of Theorem(3.4) is not true

Example (3.2)

Let Y ={i , g , h , k } , σ_1 ={ \emptyset , X ,{g}} and σ_2 = { \emptyset , X , {g , h}} . Let A={i} then σ_{1_A} = σ_{2_A} ={ \emptyset , X} . It is clear that (A , σ_{1_A} , σ_{2_A}) is D_o . But $i \neq k$ and \nexists U is $\sigma_1\sigma_2$ -D-set and $i \in U$, $k \notin U$ hence (Y , σ_1 , σ_2) is not D_o .

Definition (3.4)

Bitopology (Y, σ_1 , σ_2) is said to be D_1 if and only if for each distance points m and n there are H and K $\sigma_1\sigma_2$ -D-sets such that $m \in H$, $n \notin H$ and $m \notin K$, $n \in K$.

Theorem (3.5)

If (Y, σ_1) and (Y, σ_2) are D_1 then (Y, σ_1, σ_2) is D_1 .

Proof:

Suppose $\mathbf{i} \neq \mathbf{j}$ in X . Since (\mathbf{Y}, σ_1) , (\mathbf{Y}, σ_2) are D_1 then there exist U_1 and U_2 are σ_1 -D-sets such that $(i \in U_1, j \notin U_1)$ and $i \notin U_2$, $j \in U_2$ and V_1 and V_2 are σ_2 -D-sets such that $(i \in V_1, j \notin V_1)$ and $i \notin V_2$, $j \in V_2$. Let $U = U_1 \cup U_2$ and $V = V_1 \cup V_2$. Hence U and V are $\sigma_1 \sigma_2$ -D-sets and $i \in U$, $j \in U$, $i \in V$ and $j \in V$. Thus (Y, σ_1, σ_2) is D_1 . The following example converse of Theorem(3.4) is not true for

Example (3.3)

Suppose $Y = \{u, v, w\}\}$, $\sigma_1 = \{\emptyset, Y, \{u, v\}, \{u\}\}$ and $\sigma_2 = \{\emptyset, Y, \{v, w\}, \{w\}\}\}$. It is clear that (Y, σ_1, σ_2) is D_1 . But $u \neq w$ and $\not\equiv C_1$, C_2 are C_1 , C_2 are C_1 , C_2 are C_3 . Thus C_3 is not C_3 . Similarity we have C_3 is not C_3 .

Theorem (3.6)

If $f:(Y_1,\sigma_1,\sigma_2) \to (Y_2,\rho_1,\rho_2)$ is continuous and one to one and Y is D_1 -space then Y_1 D_1 -space.

Proof

Let Y_2 is D_1 and $x \neq y$ in Y_1 . Then there exist a, $b \in Y_2$ where $a \neq b$ f(x)=u, f(y)=v. Since f is one to one hence f(x) is not equal to (y). Since Y_2 is D_1 then there exist E and H are $\rho_1\rho_2$ -D containing in Y and $u \in E$, $v \notin E$, $u \notin H$ and $v \in H$. The inverse image of E and E are G_1 and G_2 - G_2 - G_3 because G_1 is continuous. And the inverse image of E containing G_1 and G_2 is G_3 .

Theorem(3.7)

Every subspace of D_1 -bitopological space is D_1 -bitopological space

Proof:

Suppose $(A, \sigma_{1_A}, \sigma_{2_A})$ is subspace in (M, σ_1, σ_2) . Let u and v are two different points in A thus $u, v \in M$. Since M is D_1 then there exist G and W are $\sigma_1\sigma_2$ -D-sets in M and U are U are U and U are U are U are U and U are U are U are U and U are U are U are U are U and U are U are U are U and U are U and U are U a

Theorem (3.8)

Every D_1 -bitopological space is D_o .

Proof:

Let $a \neq b$ in X . Since (X, σ_1, σ_2) is D_1 then then there exist $G = \{ \in G , b \notin G \}$ and $W = \{ a \notin W , b \in W \}$ are $\sigma_1 \sigma_2$ -D . Then (X, σ_1, σ_2) is D_0 .

4. Pairwise and weak pairwise D_k - bitopological spaces

Definition(4.1)

(N, σ_1 , σ_2) is said to be

1- pairwise T_o if and only if $\forall c, d \in \mathbb{N}$ and $c \neq d \exists K_1$ is σ_1 -open ($c \in K_1$, $d \notin K_1$) or $\exists K_2$ is σ_2 -open ($d \in K_2$, $c \notin K_2$). [4]

2- pairwise D_o if and only if \forall u, $v \in \mathbb{N}$ u \neq v \exists G_1 is σ_1 -D-set (u \in G_1 , d \notin G_1) or \exists G_2 σ_2 -D ($v \in G_2$, u \notin G_2).

Theorem (4.1)

Bitopological (X, σ_1 , σ_2) pairwise T_o if and only if pairwise D_o

Proof:

Let $x \neq y$ in X and (X, σ_1, σ_2) is pairwise T_o then there exist either A is σ_1 -open A containing x not y. Or there is B is σ_2 -open set containing x not y thus σ_1 -D-set containing x not y. Therefore X is pairwise D_o .

Let $m \neq n$ in X and (X, σ_1, σ_2) is pairwise D_o then either A is σ_1 -D-set, $m \in A$ and $n \not\in A$. Thus $A = A_1 - A_2$ such that $A_1 \neq X$ where A_1, A_2 are σ_1 -open hence $m \in A_1$ and $y \notin A_1$. Or B is σ_2 -D-set such that $m \notin B$ and $n \in B$ thus $B = B_1 - B_2$ such that $B_1 \neq X$ and B_1 , B_2 are σ_2 -open hence $m \notin B_1$ and $n \in B_1$. Therefore X is pairwise T_o .

Theorem (4.2)

Every D_o is pairwise D_o .

Proof:

Let $x \neq y$ in X and (X, σ_1, σ_2) is D_o thus $\exists G$ is $\sigma_1 \sigma_2$ -D-set where $G = \{m \in G \text{ and } n \not\in G\}$. Thus $G = A \cup B$ such that A is σ_1 -D-set and B is σ_2 -D-set thus x containing in A or not containing in B and y not containing in A . Thus there exist A is σ_1 -D-set, $A = \{x \in A \text{ and } y \notin A\}$ or there exist B is σ_2 -D-set, $B \in A$ and $B \in A$. Hence $A \in A$ and $B \in A$ is $A \in A$ and $A \in A$ an

Theorem(4.3)

If (M , σ_1 , σ_2) is pairwise- D_o and A subset of X therefore (A, σ_{1_A} , σ_{2_A}) is pairwise- D_o proof

Suppose c, d are different points in A thus $x \neq y$ in M . Since M is pairwise- D_o then either G is (σ_1 -D-set or is σ_2 -D) in M where $G = \{c \in G \text{ and } d \notin G\}$ or $G = \{c \notin G \text{ and } d \in G\}$. It is clear that $G \cap A$ is σ_{1_A} -D-set or is σ_{2_A} -D-set in A, let $G^* = G \cap A$. We have that $c \in G^*$ and $c \in G^*$ and $c \in G^*$ and $c \in G^*$. Therefore $(A, \sigma_{1_A}, \sigma_{2_A})$ is pairwise- $c \in G^*$.

A function $f:(X,\sigma_1,\sigma_2)\to (Y,\rho_1,\rho_2)$ said to be pairwise continuous if $f^{-1}(A)\in\sigma_1\cup\sigma_2$ for all $A\in\rho_1\cup\rho_2$

Theorem (4.4)

If g:(N, σ_1 , σ_2) \rightarrow (H, ρ_1 , ρ_2) is pairwise continues and one to one and Y is D_o -space then X D_o -space.

Proof:

Let H pairwise- D_o where $x \neq y$ in X. We have \exists a, b in Y, $a \neq b$ and g(x) = a, g(y) = b. Since g is one to one hence $g(x) \neq g(y)$. Since N is pairwise- D_o then there exist G is $(\rho_1$ -D-set such that $a \in G$ and $b \notin G$) or (G is ρ_2 -D-set such that $a \notin G$ and $b \in G$. Hence then there exist S_1 , S_2 are ρ_1 open or ρ_2 -open such that $S_1 \neq H$ and $G = S_1 - S_2$. We have S_1 , $S_2 \in \rho_1 \cup \rho_2$. Since f is pairwise continuous thus the inverse image of S_1 , S_2 are σ_1 -open or σ_2 -open sets in N. Therefore the inverse image of S_1 , S_2 containing in $\sigma_1 \cup \sigma_2$ such that $\sigma_1 \cup \sigma_3$ such that $\sigma_2 \cup \sigma_4$ or (G) is $\sigma_3 \cup \sigma_4$ or (G) not equal to N thus $\sigma_3 \cup \sigma_4$ is $\sigma_4 \cup \sigma_4$ such that $\sigma_4 \cup \sigma_4$ or (G) is σ_4

Definition(4.3)

A space (K, σ_1, σ_2) is said to be

i) Weak pairwise T_o if and only if \forall m and n are distinct points in k \exists U is σ_1 -open set or σ_2 -open , m \in U and n \notin U . [4]

ii) Weak pairwise D_0 if and only if \forall m and n are distinct points in K \exists U is σ_1 -D-set or σ_2 -D-set m \in U and $n \notin$ U.

Remark(4.1)

Every pairwise D_o is weak pairwise D_o

Theorem(4.5)

A bitopological space (X, σ_1 , σ_2) is weak pairwise T_o if and only if weak pairwise D_o

Proof:

Similarity to Theorem (4.1)

Remark(4.2)

Every D_o is Weak pairwise D_o .

Theorem (4.6)

If (M, σ_1) or (M, σ_2) D_0 then (M, σ_1, σ_2) is waek pairwise- D_0 .

Proof:

Suppose x and y are different points in X. Since (M, σ_1) or (M, σ_2) are D_o thus there exist W is σ_1 -D-set or σ_2 -D-set such that $x \in W$ and $y \in W$. Therefore (M, σ_1, σ_2) is weak pairwise- D_o .

But the converse is not true for example

Example (4.1)

Let M ={ c , d , e } such that σ_1 ={ Ø , M ,{c}} and σ_2 = { Ø , M ,{d}} . It is clear that M is weak pairwise- D_o but (M , σ_1) and (M , σ_2) not D_o

Theorem(4.7)

If (X, σ_1 , σ_2) is waek pairwise- D_o and A subset of X then (A, σ_{1_A} , σ_{2_A}) is weak pairwise- D_o

Proof: Clear

Remark (2.1)

If σ_1 or σ_2 discrete then (X, σ_1, σ_2) is weak pairwise- D_o

Definition(4.4)

 (M, σ_1, σ_2) is said to be

i) pairwise D_1 -space if and only if $\forall i, j \in M$ where $i \neq j$. $\exists \sigma_1$ -D-set U and σ_2 -D-set V where $U = \{i \in U, j \notin U\}$ and $V \in \{i \notin V, j \in V\}$

ii) Weak pairwise D_1 -space if and only if \forall i, j \in M where i \neq j. \exists σ_1 -D-set A and σ_2 -D-set B such that either i \in A , j \notin A and j \in B, i \notin B or i \in B , j \notin B and i \notin A , j \in A .

Theorem (4.8)

- 1) Every D_1 is pairwise D_o .
- 2) Every pairwise D_1 is weak pairwise D_o .
- 3) Every weak pairwise D_1 is pairwise D_0 .

Proof:

- 1) Let $x \neq y$ in X . And (X, σ_1, σ_2) is D_1 thus there exist A and B are $\sigma_1\sigma_2$ -D-sets, A containing x not y, B containing y not $x, y \in B$. Then $A = S \cup O$ and $B = G \cup W$ such that S and G are σ_1 -D-sets, O and W are σ_2 -D-sets hence there exits S is σ_1 -D-set such that $x \in S$, $y \notin S$ or O is σ_2 -D-set such that $x \notin O$, $y \in O$. We have X is pairwise D_o .
- 2) Suppose $x \neq y$ in W. And (W, σ_1, σ_2) is pairwise D_1 thus there exist A is σ_1 -D-set and B is σ_2 -D-set such that $x \in A$, $y \notin A$ and $x \notin B$, $y \in B$. We have W is pairwise D_0 .
- 3) Let $x \neq y$ in X . And (X, σ_1, σ_2) is weak pairwise D_1 thus there exist K is σ_1 -D-set and G is σ_2 -D-set such that either $K = \{x \in K, y \notin K\}$ and $G = \{x \notin G, y \in G\}$ or $G = \{x \in G, y \notin G\}$ and $K = \{x \notin K, y \in K\}$. Hence there exist K is σ_1 -D-set such that $x \in K$, $y \notin K$ or there exist G is σ_2 -D-set such that $x \notin G$, $y \in G$. We have (X, σ_1, σ_2) is pairwise D_o

Theorem (4.9)

If h: $(M, \sigma_1, \sigma_2) \rightarrow (N, \rho_1, \rho_2)$ is pairwise continues and one to one and N is D_1 then M is D_1 .

Proof:

Similarity to Theorem (4.4)

Theorem (4.10)

If (X, σ_1, σ_2) is waek pairwise- D_1 and A subset of X then (A, τ_A, σ_A) is weak pairwise- D_1 **Proof: clear**

The following diagram explain the relations of types of D_K for K=0, 1, as shown in Fig. 1.

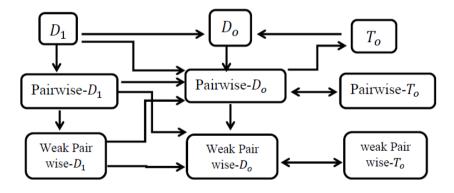


Fig. 1. Relationship of types of D_K

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