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# Analyze a temperature and MHD peristaltic flow of sutterby fluid through a porous wavechannel in a rotating frame

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## ABSTRACT

The aim of this paper is to analyze the temperature and magnetohydrodynamic (MHD) peristaltic flow of non-Newtonian Sutterby fluid through a porous wavechannel under the influence of rotation. The problem formula is non-linear and non-homogeneous partial differential equations. By using the perturbation technique, we solved the momentum equation under the assumptions of a long wavelength and an extremely low Reynolds number. After getting the solution, we have used the "Mathematica 13" program to analyze the results through graphs, and it have been studied the effect of the rotation, magnetic field, viscosity of the fluid and average radius of the tube on the fluid movement and its temperature.

MSC..

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## 1. Introduction

In industrial and physiological processes, the non-Newtonian fluids are acknowledged more than viscous fluids. There are several types of non-Newtonian substances that can be seen in nature such like shampoo, paints, ketchup and blood, Sutterby fluid model (which is a non-Newtonian fluid) represents the high-polymer aqueous solutions [6]. Porous media can be distinguished through its spatial properties such as permeability, porosity, hardness and so many other properties, but one of the most recognized characteristics is permeability and porosity [5]. There are many materials in porous media such as man-made materials like cement, natural materials such as rocks, last but not least biological tissues such as bones. Porous media is used in many applications in science and engineering fields. The flow of fluids through the porous medium faces movement's obstruction due to the friction of the fluid with the walls of the porous medium [5]. AL-Khafajy et al. in [3], studied variable viscosity effects of mass transfer on the MHD oscillatory flow of the Carreau fluid through a porous channel. The most important subject in fluid kinematics through a channel is the magnetic field which is generated from an electric current. It has encouraged other researchers to write about its uses in a variety of science, including the natural and health science. AL-Khafajy in [2], analyze the mathematical model of the effect of peristalsis flow from the MHD of a Jeffrey fluid across a cylindrical polar coordinates system for the slanted porous channel at different temperatures and concentrations with variable

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viscosity for the fluid. The peristaltic flow of a fluid through a channel while a magnetic field is present has been the subject of numerous studies, Reddy in [7], found that when permeability parameter increases, the fluid’s velocity increases, but when magnetic parameter increases, the fluid’s velocity decreases. Hayat et al. in [4], found out that the fluid’s velocity has increased near the flow channel wall when the magnetic parameter has been increased, while the fluid’s velocity decreased in the center of the channel. Riaz et al. in [8], found out that the velocity of the fluid decreased with the magnetic parameter. Recently, interest has begun to investigate the effect of the temperature on liquid’s moveableness proceed along the channel, as most researchers agree that increasing in the temperature leads to increasing in the fluid’s velocity. There is a major concept in biological processes and industrial fluid transport is heat transfer as an example, keep up the body’s temperature is one of the most required roles of the cardiovascular system and air that goes into the lungs must also be tempered to the temperature of the body. Mohammed and Hummady in [6], studied the effects of the rotation on heat transfer for peristaltic transport of Sutterby fluid in an asymmetric channel. These studies inspire us to present a mathematical model to analyze the temperature and hydrodynamic peristaltic flow of a Sutterby fluid through a porous wave channel under the influence of rotation.

### 2. Mathematical Formulation

Consider a peristaltic flow of a Sutterby fluid through a porous wavechannel which the equation for the flow channel wall is  $\pm \left( d - \bar{\phi} \sin^2 \left( \frac{\pi}{\omega} (\bar{X} - s\bar{t}) \right) \right)$  in two-dimensional Cartesian coordinates, where the positive sign represents the upper wall while the negative sign represents the lower wall of the channel. Where  $d$  is the average radius of the tube,  $\bar{\phi}$  is the amplitude of a peristaltic wave,  $\omega$  is a wavelength,  $s$  is a wave propagation speed, and  $\bar{t}$  is a time. The fluid is electrically conducted by an external magnetic field,  $B = (0, B_0, 0)$ . The fluid rotates with a uniform angular velocity  $\Omega$  about the z-axis. Due to the wave motion of the flow channel wall (contraction and relaxation), the fluid moves in the form of a peristaltic flow in the middle of the channel. The basic governing equations of the system are (continuity, momentum, and temperature equation), given by:

$$\nabla \cdot \bar{U} = 0. \tag{continuity equation} \tag{1}$$

$$\rho(\bar{U} \cdot \nabla)\bar{U} + \rho \left( \Omega(\Omega \times \bar{U}) + 2\Omega \times \frac{\partial \bar{U}}{\partial \bar{t}} \right) = \nabla \bar{S} - \frac{\mu}{K} \bar{U} + \mu_e \cdot \bar{B} \times \bar{j} \tag{momentum equation} \tag{2}$$

$$\rho c_p(\bar{U} \cdot \nabla)T = H \cdot \nabla^2 T + \tau \cdot (\nabla \bar{U}) - G(T - T_0) \tag{temperature equation} \tag{3}$$

The definition of Sutterby fluid equation [1] is:

$$\bar{S} = -\bar{p}I + \tau$$

$$\tau = \frac{\mu}{2} \left[ \frac{\sinh^{-1}(b\dot{\gamma})}{b\dot{\gamma}} \right]^n (\nabla \bar{U} + (\nabla \bar{U})^T). \tag{4}$$

Here  $\bar{U}$  is velocity filed,  $\Omega$  is the rotation parameter,  $\bar{S}$  is the Cauchy stress tensor,  $\bar{p}$  is the pressure,  $I$  is the unit tensor,  $\tau$  is the extra stress tensor,  $\mu_0$  is the zero shear rate viscosity, and  $\dot{\gamma}$  is the second invariant strain tensor which is defined as  $\dot{\gamma} = \frac{1}{\sqrt{2}} \sqrt{\text{trac}(\nabla \bar{U} + (\nabla \bar{U})^T)^2}$ , where  $(\nabla \bar{U})$  is a gradient of the fluid velocity, and  $(\nabla \bar{U})^T$  is the transpose of the gradient velocity in the Cartesian coordinates system (x,y,z). When  $|b\dot{\gamma}| \ll 1$ , we have  $\sinh^{-1}(b\dot{\gamma}) \approx (b\dot{\gamma}) - \frac{(b\dot{\gamma})^3}{6}$ , so that equation (4) become:

$$\tau \approx \frac{\mu}{2} \left[ 1 - \frac{nb^2}{6} (\dot{\gamma})^2 \right] (\nabla \bar{U} + (\nabla \bar{U})^T). \tag{5}$$

### 3. Solution of Problem

Let  $\bar{U}_1$  and  $\bar{U}_2$  be the respective the components of velocity in the radial and axial directions in the fixed frame, respectively. The equations (1), (2), and (3) may be written as follows:

$$\frac{\partial \bar{U}_1}{\partial \bar{x}} + \frac{\partial \bar{U}_2}{\partial \bar{y}} = 0, \tag{6}$$

$$\rho \left( \frac{\partial \bar{U}_1}{\partial \bar{t}} + \bar{U}_1 \frac{\partial \bar{U}_1}{\partial \bar{x}} + \bar{U}_2 \frac{\partial \bar{U}_1}{\partial \bar{y}} \right) - \Omega \rho \left( \Omega \bar{U}_1 + 2 \frac{\partial \bar{U}_2}{\partial \bar{t}} \right) = -\frac{\partial \bar{p}}{\partial \bar{x}} + \frac{\partial \bar{\tau}_{XX}}{\partial \bar{x}} + \frac{\partial \bar{\tau}_{XY}}{\partial \bar{y}} - \sigma B_0^2 \bar{U}_1 - \frac{\mu}{K} \bar{U}_1, \tag{7}$$

$$\rho \left( \frac{\partial \bar{U}_2}{\partial \bar{t}} + \bar{U}_1 \frac{\partial \bar{U}_2}{\partial \bar{x}} + \bar{U}_2 \frac{\partial \bar{U}_2}{\partial \bar{y}} \right) - \Omega \rho \left( \Omega \bar{U}_2 - 2 \frac{\partial \bar{U}_1}{\partial \bar{t}} \right) = -\frac{\partial \bar{p}}{\partial \bar{y}} + \frac{\partial \bar{\tau}_{\bar{y}\bar{x}}}{\partial \bar{x}} + \frac{\partial \bar{\tau}_{\bar{y}\bar{y}}}{\partial \bar{y}} - \frac{\mu}{\bar{K}} \bar{U}_2, \tag{8}$$

$$\rho c_p \left( \frac{\partial T}{\partial \bar{t}} + \bar{U}_1 \frac{\partial T}{\partial \bar{x}} + \bar{U}_2 \frac{\partial T}{\partial \bar{y}} \right) = H \left( \frac{\partial^2 T}{\partial \bar{x}^2} + \frac{\partial^2 T}{\partial \bar{y}^2} \right) + \frac{\partial \bar{U}_1}{\partial \bar{x}} (\bar{\tau}_{\bar{x}\bar{x}}) + \frac{\partial \bar{U}_1}{\partial \bar{y}} (\bar{\tau}_{\bar{x}\bar{y}}) + \frac{\partial \bar{U}_2}{\partial \bar{x}} (\bar{\tau}_{\bar{y}\bar{x}}) + \frac{\partial \bar{U}_2}{\partial \bar{y}} (\bar{\tau}_{\bar{y}\bar{y}}) - G(T - T_0), \tag{9}$$

where,  $\Omega, B_0, \sigma, \bar{K}, \rho, C_p, H,$  and  $G$  refer to "rotation parameter, magnetic field, electric conductivity, permeability, fluid density, specific heat, thermal conductivity, and heat source", respectively. The following relations are for converting from the test frame  $(\bar{X}, \bar{Y})$  to the wave frame  $(\bar{x}, \bar{y})$ :

$$\bar{u}_1(\bar{x}, \bar{y}) = \bar{U}_1(\bar{X} - s\bar{t}, \bar{Y}, \bar{t}) - s, \bar{u}_2(\bar{x}, \bar{y}) = \bar{U}_2(\bar{X} - s\bar{t}, \bar{Y}, \bar{t}), \bar{p}(\bar{x}, \bar{y}) = \bar{P}(\bar{X} - s\bar{t}, \bar{Y}, \bar{t}) \tag{10}$$

where  $(\bar{u}_1, \bar{u}_2)$  and  $(\bar{U}_1, \bar{U}_2)$  are velocity components and  $\bar{p}$  is the pressure in a frame wave.

#### 4. Method of Solution

In order to simplify the governing equations of the problem, we might introduce the following dimensionless transformations as follow:

$$\left. \begin{aligned} x = \frac{\bar{x}}{\omega}, y = \frac{\bar{y}}{d}, u_1 = \frac{\bar{u}_1}{s}, u_2 = \frac{\omega \bar{u}_2}{sd}, p = \frac{d^2 \bar{p}}{\mu \omega s}, R_e = \frac{\rho s d}{\mu}, w = \frac{\bar{w}}{d}, \Psi = \frac{\bar{\Psi}}{ds}, Q_1 = \frac{\bar{Q}_1}{ds}, \\ q_1 = \frac{\bar{q}_1}{ds}, \epsilon = \frac{nb^2 s^2}{2d^2}, \delta = \frac{d}{\omega}, \phi = \frac{\bar{\phi}}{d}, \tau_{xx} = \frac{\omega \bar{\tau}_{xx}}{\mu s}, \tau_{xy} = \frac{d \bar{\tau}_{xy}}{\mu s}, \tau_{yy} = \frac{\omega \bar{\tau}_{yy}}{\mu s}, \\ M_e^2 = \frac{d^2}{\mu} \sigma B_0^2, H_c = \frac{G d^2}{\mu c_p}, D_a = \frac{\bar{K}}{d^2}, \theta = \frac{T - T_0}{T_1 - T_0}, P_r = \frac{\mu c_p}{H}, E_c = \frac{s^2}{c_p(T_1 - T_0)} \end{aligned} \right\} \tag{11}$$

where  $R_e$  "Reynolds number",  $\phi$  "amplitude ratio",  $\delta$  "dimensionless wave number",  $\Psi$  "stream function",  $q_1$  "rate of flow",  $\epsilon$  "Sutterby fluid parameter",  $D_a$  "Darcy number",  $\theta$  "dimensionless temperature",  $M_e$  "Magnetic parameter",  $H_c$  "heat source parameter",  $E_c$  "Eckert number", and  $P_r$  "Prandtl number". Substituting equations (10,11) into equations (6-9), we will obtain:

$$\frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} = 0, \tag{12}$$

$$R_e \delta \left( (u_1 + 1) \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial y} \right) - \frac{\rho d^2}{\mu} \Omega^2 (u_1 + 1) = -\frac{\partial p}{\partial x} + \delta^2 \frac{\partial \tau_{xx}}{\partial y} + \frac{\partial \tau_{xy}}{\partial y} - \left( M_e^2 + \frac{1}{D_a} \right) (u_1 + 1), \tag{13}$$

$$R_e \delta^3 \left( (u_1 + 1) \frac{\partial u_2}{\partial x} + u_2 \frac{\partial u_2}{\partial y} \right) - \delta^2 \frac{\rho d^2}{\mu} \Omega^2 u_2 = -\frac{\partial p}{\partial y} + \delta^2 \frac{\partial \tau_{yx}}{\partial y} + \delta^2 \frac{\partial \tau_{yy}}{\partial y} - \delta^2 \frac{1}{D_a} u_2, \tag{14}$$

$$R_e \delta \left( (u_1 + 1) \frac{\partial \theta}{\partial x} + u_2 \frac{\partial \theta}{\partial y} \right) = \frac{1}{P_r} \left( \delta^2 \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) + E_c \left( \delta^2 \frac{\partial u_1}{\partial x} (\tau_{xx}) + \frac{\partial u_1}{\partial y} (\tau_{xy}) + \delta^2 \frac{\partial u_2}{\partial x} (\tau_{yx}) + \delta^2 \frac{\partial u_2}{\partial y} (\tau_{yy}) \right) - H_c \theta. \tag{15}$$

The component of extra stress of Sutterby's fluid be as the form:

$$\tau_{xy} = \left[ 1 - \epsilon \left\{ 2\delta^2 \left( \frac{\partial u_1}{\partial x} \right)^2 + 2\delta^2 \left( \frac{\partial u_2}{\partial y} \right)^2 + \left( \frac{\partial u_1}{\partial y} + \delta^2 \frac{\partial u_2}{\partial x} \right)^2 \right\} \right] \left( \frac{\partial u_1}{\partial y} + \delta^2 \frac{\partial u_2}{\partial x} \right). \tag{16}$$

The associated dimensionless boundary conditions in the wave frame are:

$$u_1 = -1 \text{ at } y = \pm w = \pm(1 - \phi \sin^2(\pi x))$$

$$\theta = 0 \text{ at } y = -w = -1 + \phi \sin^2(\pi x), \text{ and } \theta = 1 \text{ at } y = w = 1 - \phi \sin^2(\pi x).$$

Because of the flow channel's structure, we assume the wavelength  $\delta$  is too small ( $\delta \ll 1$ ). And simplification the equations (13)-(16) by neglecting those parts where this parameter appears, so that we get:

$$-\frac{\rho d^2}{\mu} \Omega^2 (u_1 + 1) = -\frac{\partial p}{\partial x} + \frac{\partial}{\partial y} \tau_{xy} - \left( M_e^2 + \frac{1}{D_a} \right) (u_1 + 1), \tag{17}$$

$$-\frac{\partial p}{\partial y} = 0, \tag{18}$$

$$\frac{1}{P_r} \frac{\partial^2 \theta}{\partial y^2} + E_c \tau_{xy} \left( \frac{\partial u_1}{\partial y} \right) - H_c \theta = 0, \tag{19}$$

$$\tau_{xy} = \left[ \frac{\partial u_1}{\partial y} - \epsilon \left( \frac{\partial u_1}{\partial y} \right)^3 \right]. \tag{20}$$

By substituting equation (20) into equation (17) and equation (19), we obtain:

$$-\frac{\rho d^2}{\mu} \Omega^2 (u_1 + 1) = -\frac{\partial p}{\partial x} + \frac{\partial^2 u_1}{\partial y^2} - 3\epsilon \left( \frac{\partial u_1}{\partial y} \right)^2 \frac{\partial^2 u_1}{\partial y^2} - \left( M_e^2 + \frac{1}{D_a} \right) (u_1 + 1) \tag{21}$$

$$\frac{\partial^2 \theta}{\partial y^2} - P_r H_c \theta = P_r E_c \epsilon \left( \frac{\partial u_1}{\partial y} \right)^4 - P_r E_c \left( \frac{\partial u_1}{\partial y} \right)^2 \tag{22}$$

**4.1 Rate of Volume Flow**

The instantaneous volume flow rate in fixed coordinates system given by:

$$\hat{Q} = \int_{-W}^W \bar{U}_1(\bar{X}-s\bar{t}, \bar{Y}, \bar{t}) d\bar{Y} \tag{23}$$

Using the transformation  $(\bar{u}_1(\bar{x}, \bar{y}) + s)$  into equation (23) and then integrating it, we get:

$$\hat{Q} = \bar{q} + s(W + W) = \bar{q} + 2sW \tag{24}$$

Where  $\bar{q} = \int_{-W}^W \bar{u}_1(\bar{x}, \bar{y}) d\bar{y}$

The time mean flow rate over a period  $T = \frac{\omega}{s}$  at a fixed position is defined as:

$$\bar{Q} = \frac{1}{T} \int_0^T \hat{Q} d\bar{t}. \tag{25}$$

Substituting equation (24) in equation (25), we will obtain:

$$\bar{Q} = \frac{1}{T} \int_0^T (\bar{q} + 2sW) d\bar{t} = \bar{q} + 2s(d - \frac{\bar{\phi}}{2}). \tag{26}$$

By using (11) into equation (26), we get:

$$dsQ = dsq + 2s(d - \frac{d\phi}{2}). \tag{27}$$

The non-dimensional equation (27) has writing as:

$$Q = q + 2 - \phi,$$

then  $q = Q + \phi - 2$ .

Where  $q$  is the dimensionless volume flow rate in the wave frame has the form:

$$dsq = \int_{-W}^W s u_1 dy \rightarrow q = \int_{-W}^W u_1 dy$$

**4.2 Velocity Function**

The equation (18) shows that  $p$  depends only on  $x$ . Equation (21) becomes as:

$$\frac{\partial^2 u_1}{\partial y^2} - Au_1 = \frac{dp}{dx} + 3\epsilon \left( \frac{\partial u_1}{\partial y} \right)^2 \frac{\partial^2 u_1}{\partial y^2} + A, \quad \text{where } A = M_e^2 + \frac{1}{Da} - \frac{\rho d^2}{\mu} \Omega^2 \tag{28}$$

Because equation (28) is a non-linear differential equation and it's difficult to find an exact solution, so we use the perturbation technique to find the problem solution, as follows:

$$u_1 = u_{10} + \epsilon u_{11} + O(\epsilon^2), \tag{29}$$

$$p = p_0 + \epsilon p_1 + O(\epsilon^2), \tag{30}$$

$$\Psi = \Psi_0 + \epsilon \Psi_1 + O(\epsilon^2), \tag{31}$$

substituting equations (29) and (30) into equation (28), then by equating the similar powers of  $\epsilon$ , we get the following results displayed as below:

***i - Zero-order system ( $\epsilon^0$ )***

$$\frac{\partial^2 u_{10}}{\partial y^2} - Au_{10} = \frac{dp_0}{dx} + A. \tag{32}$$

The associated boundary conditions  $u_{10} = -1$  at  $y = \pm h = \pm(1 - \phi \sin^2(\pi x))$

**ii - First-order system ( $\epsilon^1$ )**

$$\frac{\partial^2 u_{11}}{\partial y^2} - Au_{11} = \frac{dp_1}{dx} + 3 \left( \frac{\partial u_{10}}{\partial y} \right)^2 \frac{\partial^2 u_{10}}{\partial y^2}. \tag{33}$$

The associated boundary conditions  $u_{11} = 0$  at  $y = \pm h = \pm(1 - \phi \sin^2(\pi x))$ .

By substituting the solution of equations (32) and (33) in to equation (29), we obtain:

$$u_1 = \frac{e^{\sqrt{A}h} \left( \frac{dp_0}{dx} \right)}{A(1+e^{2\sqrt{A}h})} \left( e^{\sqrt{A}y} + e^{-\sqrt{A}y} \right) - \frac{A + \left( \frac{dp_0}{dx} \right)}{A} + \epsilon \left( e^{\sqrt{A}y} + e^{-\sqrt{A}y} \right) \left( \frac{1}{8A^2(1+e^{2\sqrt{A}h})^4} e^{\sqrt{A}h} \left( \begin{aligned} & -3 \left( \frac{dp_0}{dx} \right)^3 - 6e^{2\sqrt{A}h} \left( \frac{dp_0}{dx} \right)^3 - 6e^{4\sqrt{A}h} \left( \frac{dp_0}{dx} \right)^3 - 3e^{6\sqrt{A}h} \left( \frac{dp_0}{dx} \right)^3 - \\ & 12\sqrt{A}e^{2\sqrt{A}h} h \left( \frac{dp_0}{dx} \right)^3 + \\ & 12\sqrt{A}e^{4\sqrt{A}h} h \left( \frac{dp_0}{dx} \right)^3 + 8A \left( \frac{dp_1}{dx} \right) + 24Ae^{2\sqrt{A}h} \left( \frac{dp_1}{dx} \right) + \\ & 24Ae^{4\sqrt{A}h} \left( \frac{dp_1}{dx} \right) + 8Ae^{6\sqrt{A}h} \left( \frac{dp_1}{dx} \right) \end{aligned} \right) - \frac{1}{8A^2(1+e^{2\sqrt{A}h})^3} e^{-3\sqrt{A}y} \left( \begin{aligned} & 3e^{3\sqrt{A}h} \left( \frac{dp_0}{dx} \right)^3 - 6e^{3\sqrt{A}h+2\sqrt{A}y} \left( \frac{dp_0}{dx} \right)^3 - 6e^{\sqrt{A}(3h-2y)+2\sqrt{A}y} \left( \frac{dp_0}{dx} \right)^3 - 6e^{3\sqrt{A}h+6\sqrt{A}y} \left( \frac{dp_0}{dx} \right)^3 - \\ & 6e^{\sqrt{A}(3h-2y)+6\sqrt{A}y} \left( \frac{dp_0}{dx} \right)^3 + 3e^{\sqrt{A}(3h-2y)+8\sqrt{A}y} \left( \frac{dp_0}{dx} \right)^3 + 12\sqrt{A}e^{3\sqrt{A}h+4\sqrt{A}y} y \left( \frac{dp_0}{dx} \right)^3 - \\ & 12\sqrt{A}e^{\sqrt{A}(3h-2y)+4\sqrt{A}y} y \left( \frac{dp_0}{dx} \right)^3 + 8Ae^{3\sqrt{A}y} \left( \frac{dp_1}{dx} \right) + 24Ae^{2\sqrt{A}h+3\sqrt{A}y} \left( \frac{dp_1}{dx} \right) + \\ & 24Ae^{4\sqrt{A}h+3\sqrt{A}y} \left( \frac{dp_1}{dx} \right) + 8Ae^{6\sqrt{A}h+3\sqrt{A}y} \left( \frac{dp_1}{dx} \right) \end{aligned} \right),$$

where

$$\frac{dp}{dx} = \left( \frac{A^{3/2}(-2+2h+\phi+Q_0)}{2(\sqrt{A}h - \text{Tanh}[\sqrt{A}h])} \right) - \epsilon \left( \frac{\left( A^{3/2} e^{-4\sqrt{A}h} (1+e^{2\sqrt{A}h})^4 \text{Sech}[\sqrt{A}h] \right)^3 \left( \frac{e^{4\sqrt{A}h}(12\sqrt{A}h-8\text{Sinh}[2\sqrt{A}h]+\text{Sinh}[4\sqrt{A}h]) \left( \frac{A^{3/2}(-2+2h+\phi+Q_0)}{2(\sqrt{A}h - \text{Tanh}[\sqrt{A}h])} \right)^3}{A^{5/2}(1+e^{2\sqrt{A}h})^4} + Q_1 \right)}{(32(-\sqrt{A}h \text{Cosh}[\sqrt{A}h] + \text{Sinh}[\sqrt{A}h]))} \right).$$

**4.3 Temperature Function**

By substituting the velocity function into the heat equation (22) and then solving the compensation result, we find the temperature function (very long). By drawing the temperature function, we will discuss the effect of the main parameters on the rise or fall of the fluid temperature.

**4.4 Pressure Rise, Friction Forces, and Stream Function**

Pressure rise  $\Delta p_\Omega$  and friction forces  $F_\Omega$  on the upper and lower walls are defined as follow:

$$\Delta p_\Omega = \int_0^1 \left( \frac{dp}{dx} \right) dx,$$

$$F_\Omega = \int_0^1 h^2 \left( -\frac{dp}{dx} \right) dx.$$

We found the stream function through equation ( $\Psi = \Psi_0 + \varepsilon\Psi_1 = \int u_{10} dy + \varepsilon \int u_{11} dy$ ) and its formula after the solution is:

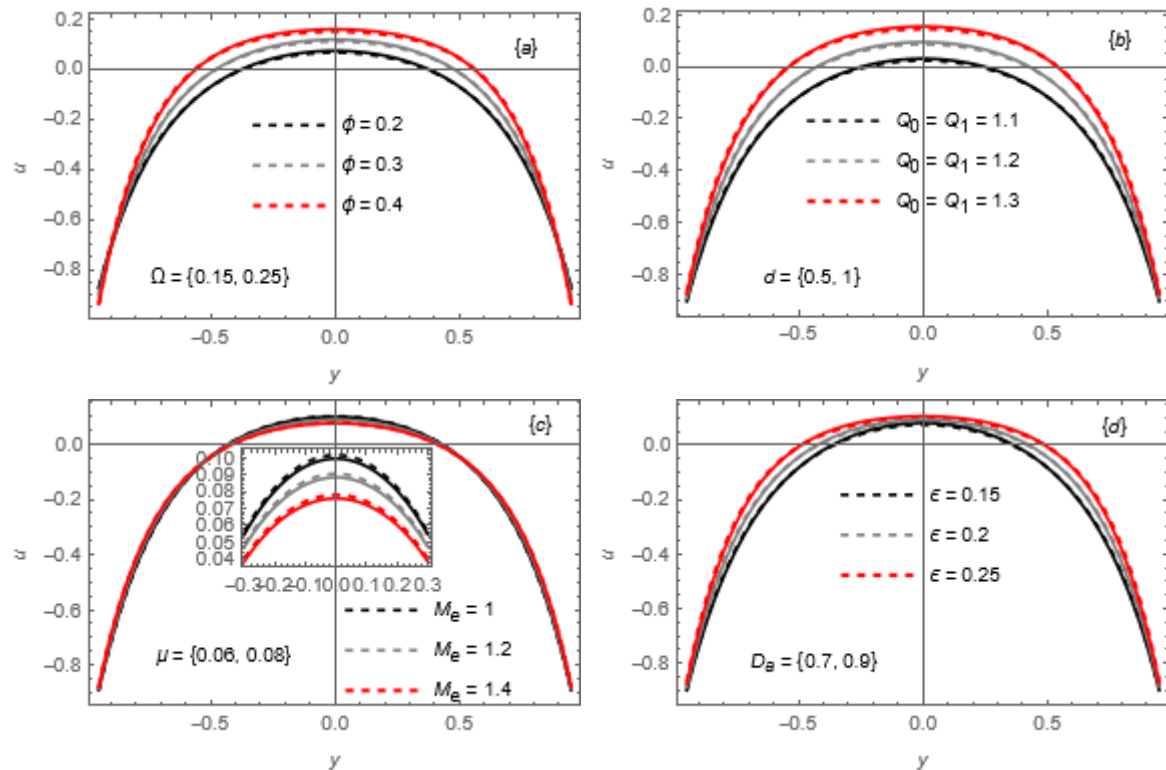
$$\Psi = -\frac{Ay + \frac{(-e^{2\sqrt{A}h - \sqrt{A}(h-y)} + e^{\sqrt{A}(h-y)})\left(\frac{dp_0}{dx}\right) + y\left(\frac{dp_0}{dx}\right)}{\sqrt{A}(1+e^{2\sqrt{A}h})}}{A} + \varepsilon \left( \frac{1}{8A^{5/2}(1+e^{2\sqrt{A}h})^4} e^{-3\sqrt{A}y} \left( -\left( \left( e^{3\sqrt{A}h} + e^{5\sqrt{A}h} - 3e^{\sqrt{A}(h+2y)} - e^{3\sqrt{A}(h+2y)} - 3e^{\sqrt{A}(7h+2y)} + 3e^{\sqrt{A}(h+4y)} + 3e^{\sqrt{A}(7h+4y)} - e^{\sqrt{A}(5h+6y)} + 12e^{\sqrt{A}(5h+4y)} \right) (-1 + \sqrt{A}(-h+y)) + 12e^{\sqrt{A}(3h+2y)} (1 + \sqrt{A}(-h+y)) + 12e^{\sqrt{A}(3h+4y)} (-1 + \sqrt{A}(h+y)) + 12e^{\sqrt{A}(5h+2y)} (1 + \sqrt{A}(h+y)) \right) \left(\frac{dp_0}{dx}\right)^3 \right) - 8Ae^{2\sqrt{A}y}(1 + e^{2\sqrt{A}h})^3 (e^{\sqrt{A}h} - e^{\sqrt{A}(h+2y)} + \sqrt{A}e^{\sqrt{A}y}y + \sqrt{A}e^{\sqrt{A}(2h+y)}y) \left(\frac{dp_1}{dx}\right) \right) \right)$$

### 5. Numerical Results and Discussion

In this section, we discuss and graphically analyze the temperature and MHD peristaltic flow of a Sutterby fluid through a porous wavechannel under the influence of rotation, by using the "Mathematica 13" program. This section divided to five subsections: the first one discusses the effect of the parameters on fluid velocity, the second one studies the effect of the parameters on pressure gradient and pressure rise, the third one analyzes the effect of the parameters on Friction Forces, the fourth one analyze the effect of the parameters on temperature, and the final subsection analyzes the effect of the parameters on stream function.

#### 5.1 Velocity Distribution

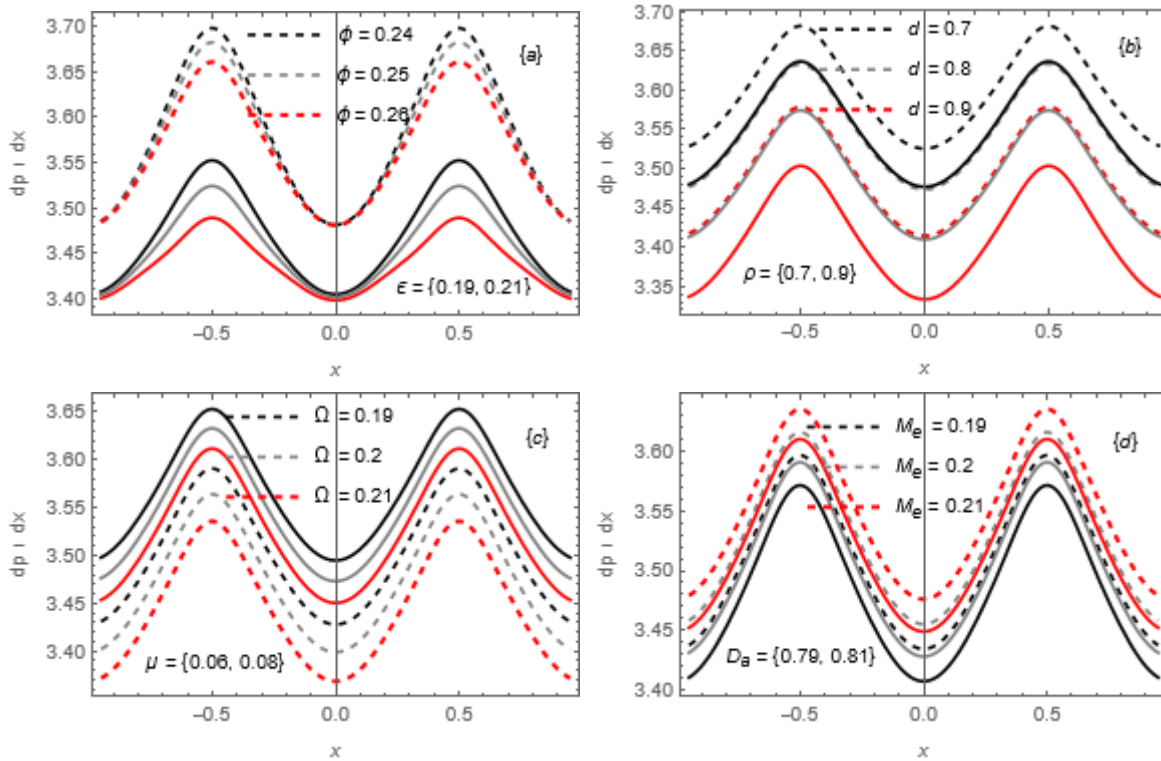
The Figs. (1a)-(1d) show the effect of parameters  $\phi, \Omega, Q_0=Q_1, d, M_e, \mu, \varepsilon$  and  $D_a$  respectively, on the distribution of velocity. Fig. (1a), shows that  $u_1$  increases in the middle of the channel, but it decreases near the channel's walls when increases the parameters  $\phi$  and  $\Omega$ , respectively. In Fig. (1b), we can see the velocity increases when the flow rate  $Q_0 = Q_1$  increases, while the velocity increases in the middle of the channel but decreases near the channel's walls when the average radius  $d$  increases. We notice in Fig. (1c),  $u_1$  decreases in the middle of the channel, but increases near the channel's walls when increases the parameters  $M_e$  and  $\mu$ , respectively. Fig. (1d), shows the velocity increases when Sutterby fluid parameter  $\varepsilon$  increases, while the velocity increases in the middle of the channel but decreases near the channel's walls when  $D_a$  increases.



**Fig. 1:** Variation of the velocity distribution for the following parameters  $\{Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \mu=0.07, \Omega=0.2, d=0.8, M_e=1.2, D_a=0.8, \epsilon=0.2, x=0.1\}$

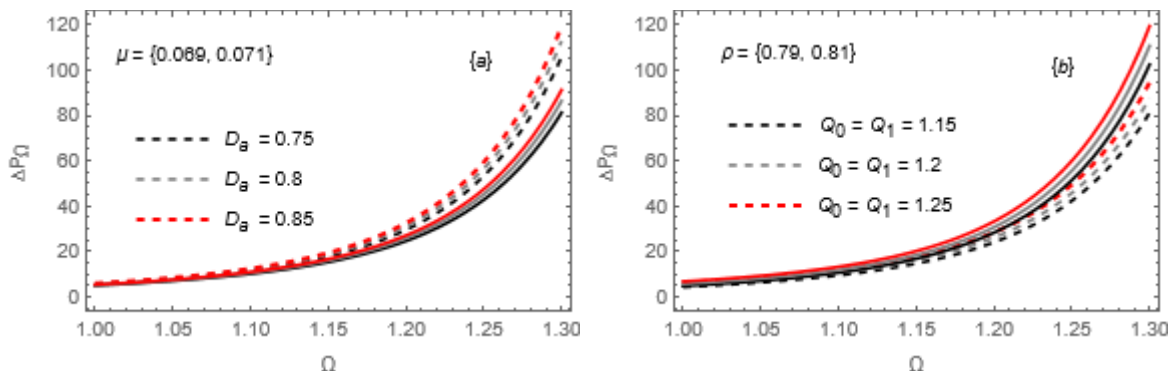
**5.2 Pressure Distribution**

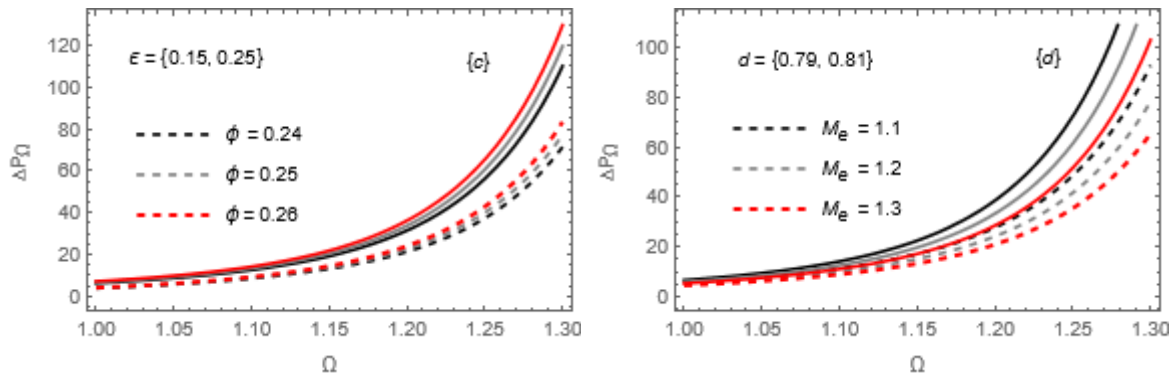
In this subsection, we discussed the influence of parameters  $\phi, \epsilon, d, \rho, \Omega, \mu, M_e$  and  $D_a$  on the pressure gradient  $dp/dx$ . In Figs. (2a) and (2b), we can see  $dp/dx$  decreases with an increase in the parameters  $\phi, \epsilon, d$  and  $\rho$ , respectively. Fig. (2c), shows the pressure gradient decreases with an increase in the rotation parameter  $\Omega$ , while  $dp/dx$  increases when the fluid’s viscosity  $\mu$  increases. We notice in Fig. (2d),  $dp/dx$  increases when the parameter  $M_e$  increases, while pressure gradient decreases when  $D_a$  increases.



**Fig. 2:** Variation of the pressure gradient for the following parameters  $\{Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \mu=0.07, \Omega=0.2, d=0.8, M_e=1.2, D_a=0.8, \epsilon=0.2\}$

Figs. (3a)-(3d) show the effects of the parameters  $D_a, \mu, Q_0=Q_1, \rho, \phi, \epsilon, M_e$  and  $d$ , respectively on the pressure rise  $\Delta p_\Omega$  vs.  $\Omega$ , through the region  $1 < \Omega < 1.3$ . Fig. (3a), shows that the pressure rise increases when Darcy number increases, while it decreases when  $\mu$  increases. In Figs. (3b) and (3c), we can see  $\Delta p_\Omega$  increases with an increase the parameters  $Q_0=Q_1, \rho, \phi$  and  $\epsilon$ . Fig. (3d), shows that  $\Delta p_\Omega$  decreases when the magnetic parameter increases, while the pressure rise increases when  $d$  increase.

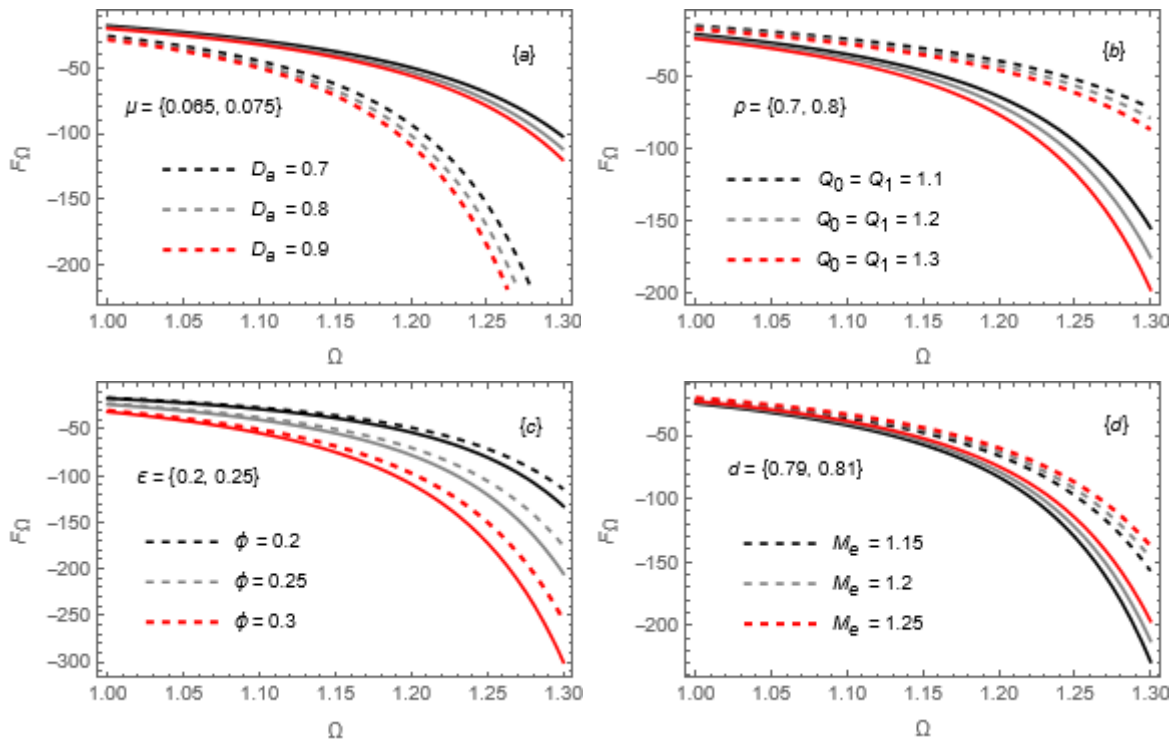




**Fig. 3:** Variation of the pressure rise for the following parameters  $\{Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \mu=0.07, d=0.8, M_e=1.2, D_a=0.8, \epsilon=0.2\}$

### 5.3 Friction Force Distribution

Figs. (4a)-(4d) shows the effect of parameters  $D_a, \mu, Q_0=Q_1, \rho, \phi, \epsilon, M_e$  and  $d$  on the friction forces  $F_\Omega$  vs.  $\Omega$ , through the region  $1 < \Omega < 1.3$ . Fig. (4a), shows that the friction forces decreases when the parameter  $D_a$  increases, while it increases with increasing the fluid’s viscosity  $\mu$ . We can see in Figs. (4b) and (4c), the friction forces decreases when the parameters  $Q_0=Q_1, \rho, \phi$  and  $\epsilon$  increases, respectively. In Fig. (4d), the friction forces increases with increasing the parameter  $M_e$ , while it decreases when the average radius  $d$  increases.



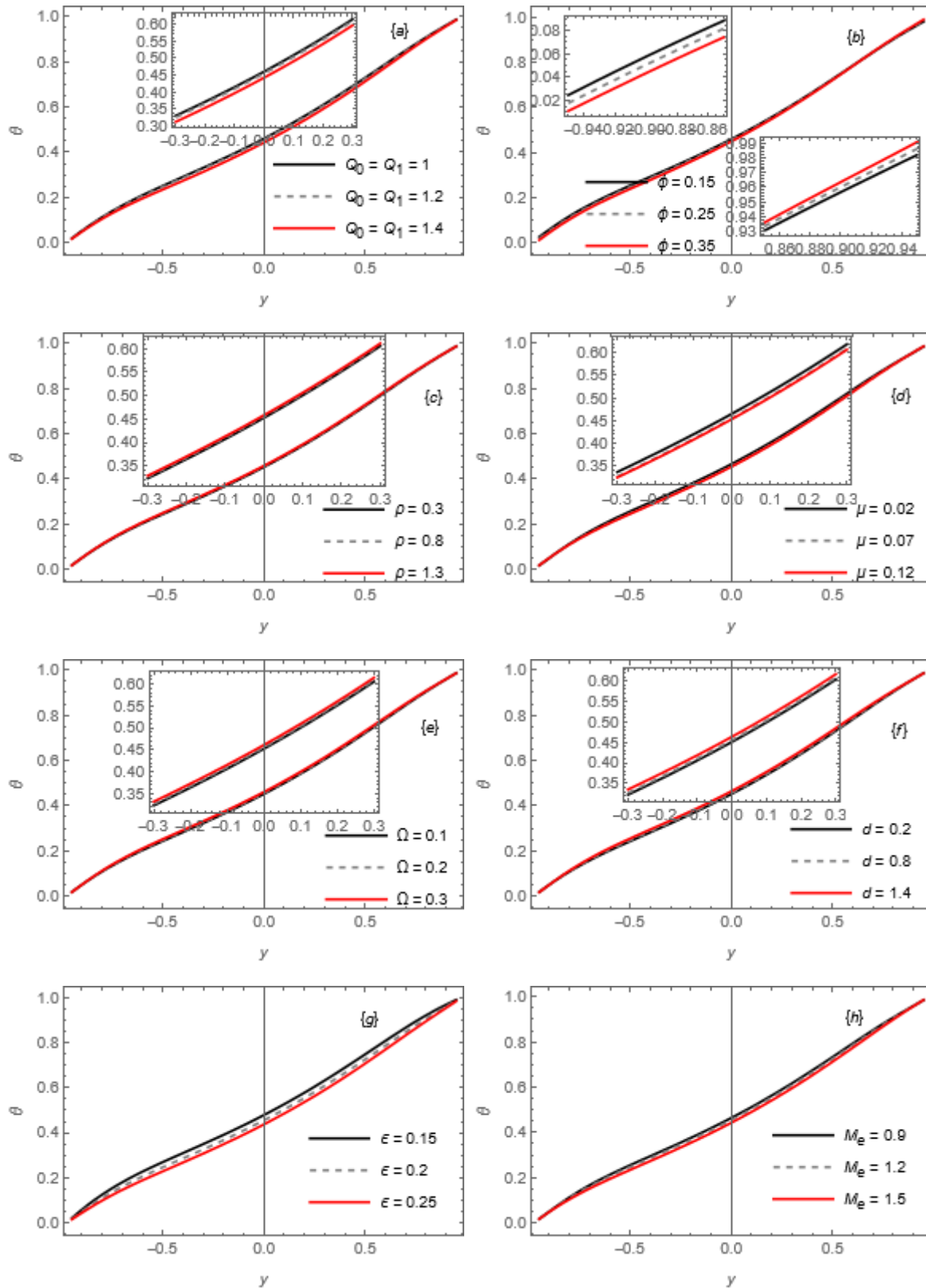
**Fig. 4:** Variance of the frictional forces for the following parameters  $\{Q_0 = Q_1 = 1.2, \phi = 0.25, \rho = 0.8, \mu = 0.07, d = 0.8, M_e = 1.2, D_a = 0.8, \epsilon = 0.2\}$

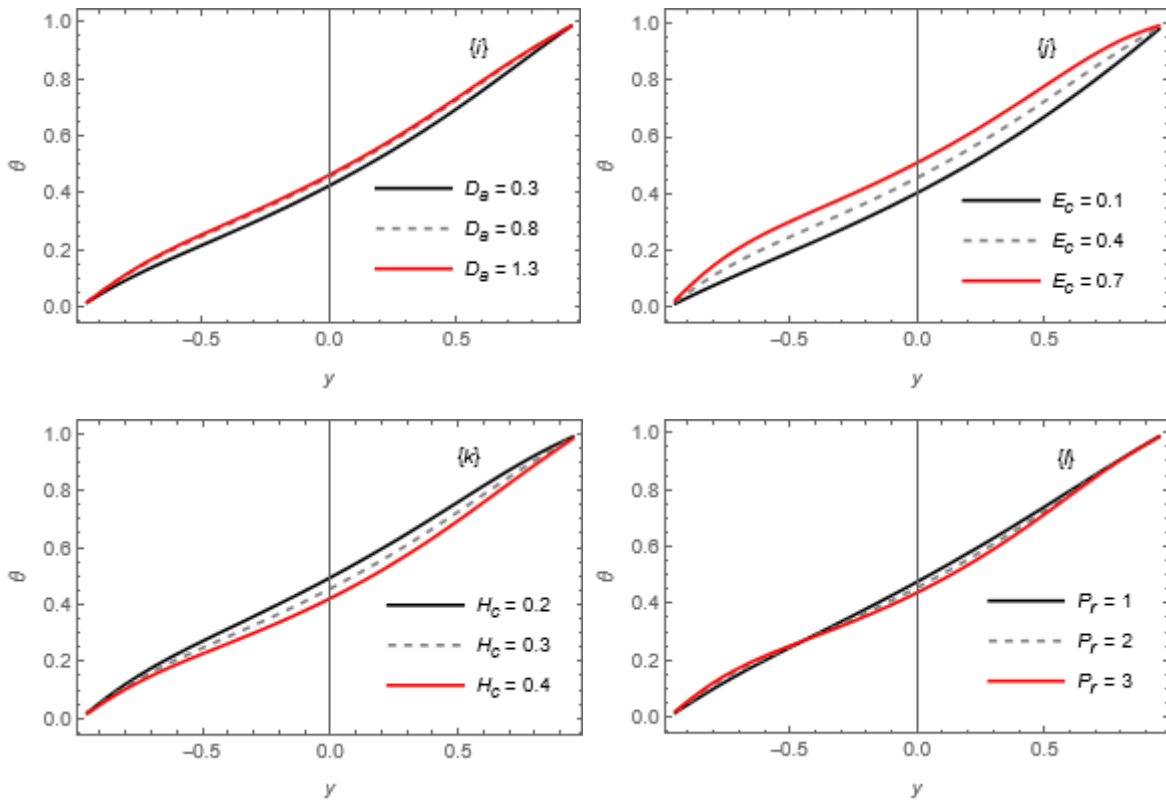
### 5.4 Temperature profile

Figs. (5a)-(5i) show the effect of parameters  $Q_0 = Q_1, \phi, \rho, \mu, \Omega, d, M_e, D_a, \epsilon, E_c, H_c$  and  $P_r$  on the temperature vs.  $y$ . Fig. (5a), shows that the temperature decreases when parameter  $Q_0 = Q_1$  increases. In Fig. (5b), shows the temperature decreases at  $y < 0$ , while increases at  $y > 0$  when  $\phi$  increases. In Figs. (5c) and (5d), we notice that the temperature increases when the fluid’s density  $\rho$  increases, while the temperature decreases when the fluid’s viscosity increases. We can see in Figs. (5e) and (5f), that the temperature increases when the parameters  $\Omega$  and  $d$



increase, respectively. Figs. (5g) and (5h), show the temperature decreases when the parameters  $\epsilon$  and  $M_e$  increase, respectively. Figs. (5i) and (5j), show that the temperature increases when the parameters  $D_a$  and  $E_c$  increase, respectively. Fig. (5k), shows that the temperature decreases when parameter  $H_c$  increases. In Fig. (5l), we can see that the temperature increases and decreases when the parameter  $P_a$  increases.

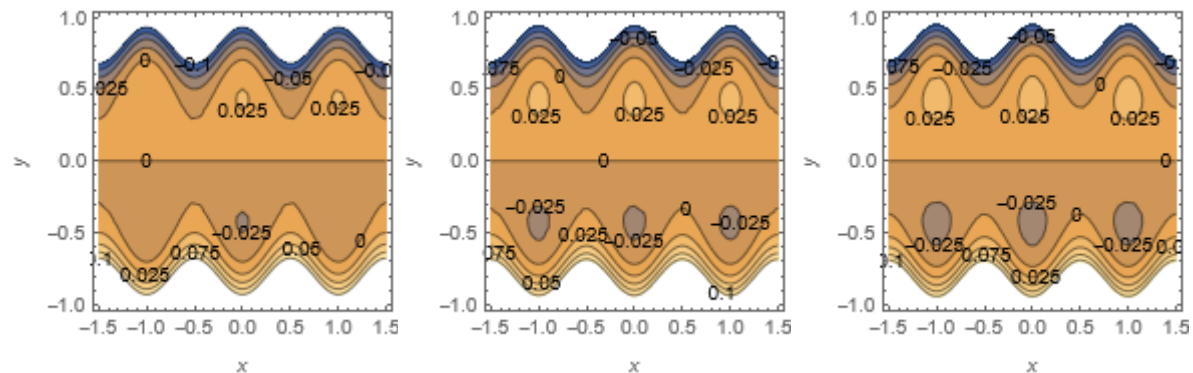




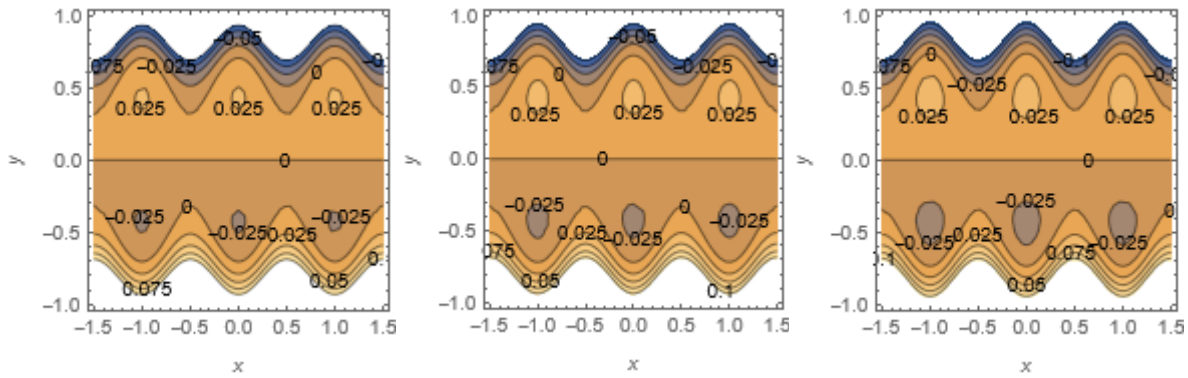
**Fig. 5:** Variation of the temperature distribution for the following parameters  $\{Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \mu=0.07, \Omega=0.2, d=0.8, M_e=1.2, D_a=0.8, \epsilon=0.2, x=0.1, E_c=0.4, H_c=0.3, P_r=2\}$

### 5.5 Trapping Phenomenon

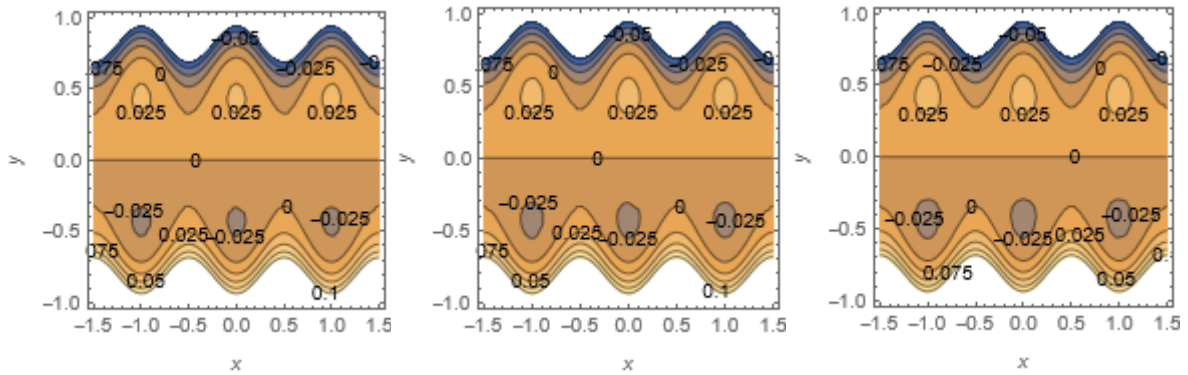
The creation of in fluid internal bolus by a closed streamline in a fluid flow is known as the trapping phenomenon. In this part we will illustrate the effect of the parameters  $Q_0=Q_1, \phi, \rho, \mu, \Omega, d, M_e, D_a$  and  $\epsilon$  on trapped bolus through a porous wavechannel. Figs. (6a)-(6c), show that the trapped bolus has increases at the lower and upper walls of the channel when the parameters  $Q_0=Q_1, \phi$  and  $\rho$  increases. Fig. (6d), shows the trapped bolus decreases when the fluid’s viscosity  $\mu$  increases. In Figs. (6e) and (6f), we can see the trapped bolus increases when the parameters  $\Omega$  and  $d$  increases. Fig. (6g), show that the trapped bolus decreases when the magnetic parameter increases. Figs. (6h) and (6i), show that the trapped bolus increases when the parameters  $D_a$  and  $\epsilon$  increases.



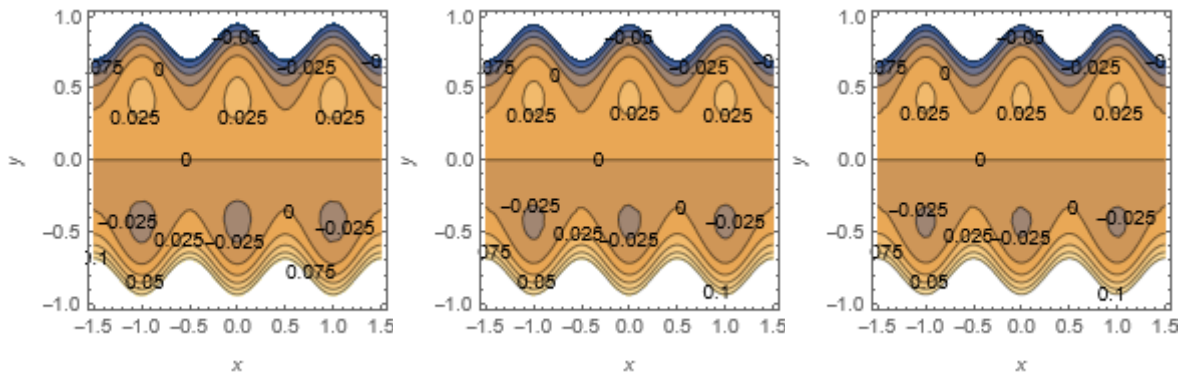
**Fig. 6a:** Stream function of  $Q_0=Q_1=\{1.192, 1.2, 1.208\}$  at  $\phi=0.25, \rho=0.8, \mu=0.07, \Omega=0.2, d=0.8, M_e=1.2, D_a=0.8, \epsilon=0.2$



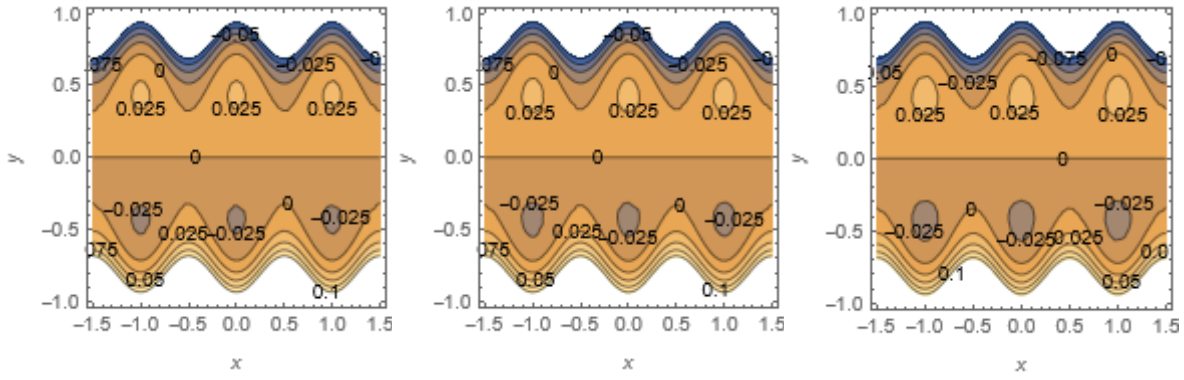
**Fig. 6b:** Stream function of  $\phi=\{0.24,0.25,0.26\}$  at  $Q_0=Q_1=1.2, \rho=0.8, \mu=0.07, \Omega=0.2, d=0.8, M_e=1.2, D_a=0.8, \epsilon=0.2$



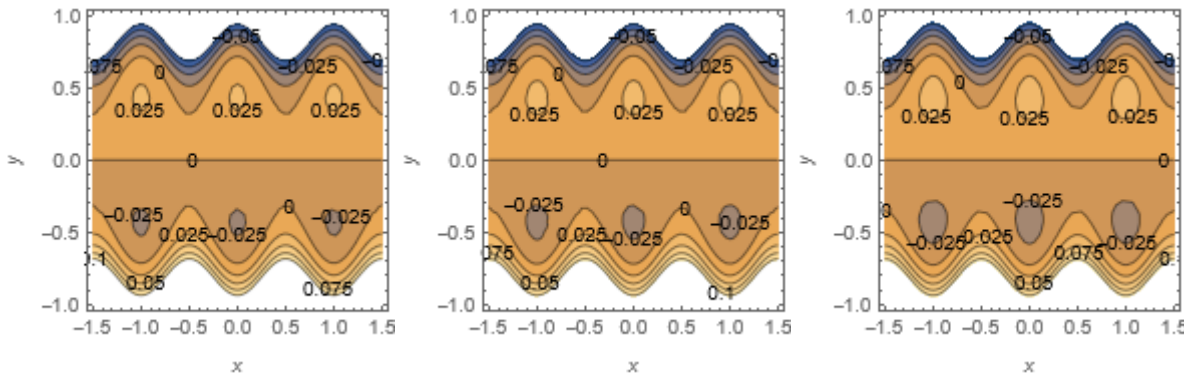
**Fig. 6c:** Stream function of  $\rho=\{0.5,0.9,1.2\}$  at  $Q_0=Q_1=1.2, \phi=0.25, \mu=0.07, \Omega=0.2, d=0.8, M_e=1.2, D_a=0.8, \epsilon=0.2$



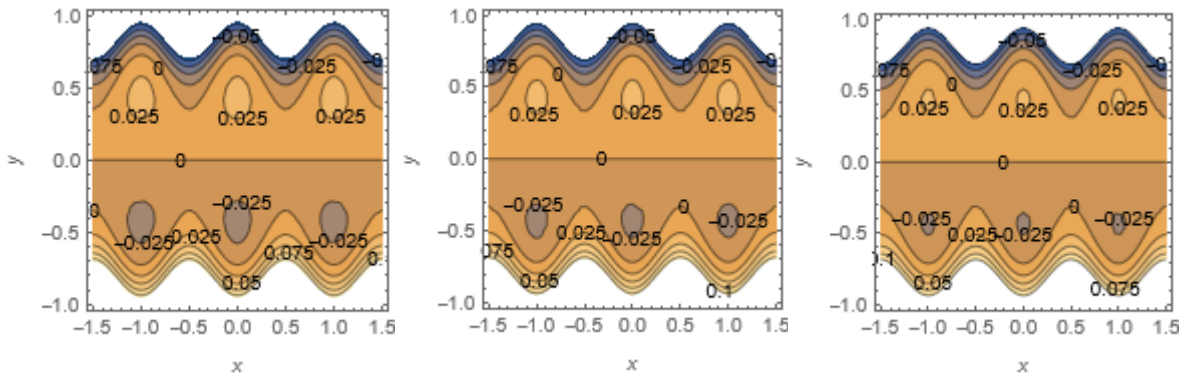
**Fig. 6d:** Stream function of  $\mu=\{0.04,0.07,0.1\}$  at  $Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \Omega=0.2, d=0.8, M_e=1.2, D_a=0.8, \epsilon=0.2$



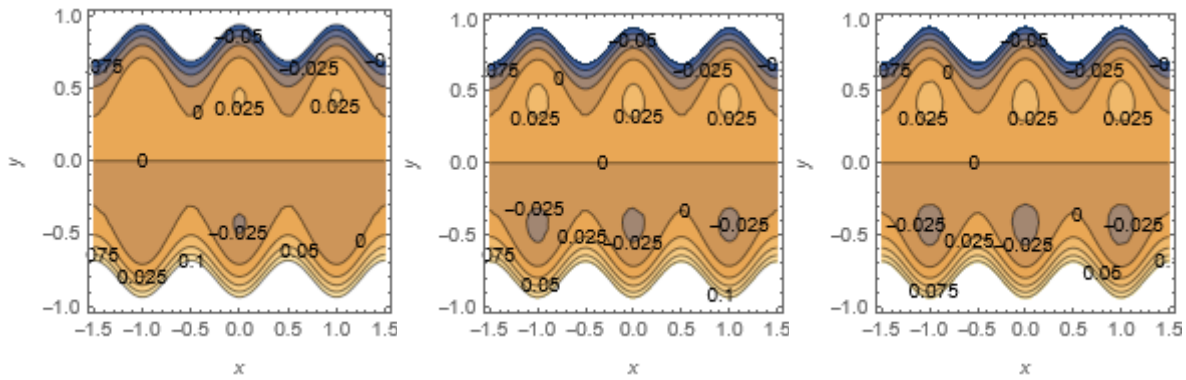
**Fig. 6e:** Stream function of  $\Omega=\{0.15,0.2,0.25\}$  at  $Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \mu=0.07, d=0.8, M_e=1.2, D_a=0.8, \epsilon=0.2$



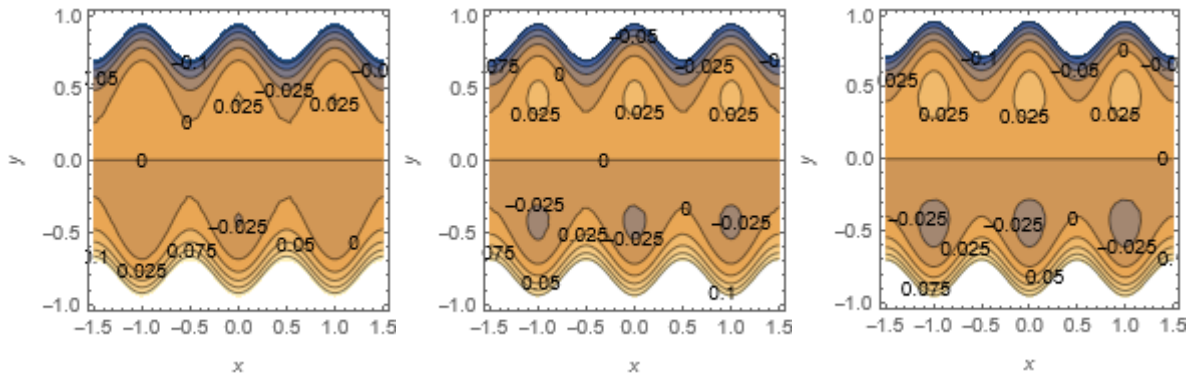
**Fig. 6f:** Stream function of  $d=\{0.5,0.8,1.1\}$  at  $Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \mu=0.07, \Omega=0.2, M_e=1.2, D_a=0.8, \epsilon=0.2$



**Fig. 6g:** Stream function of  $M_e=\{1.15,1.2,1.25\}$  at  $Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \mu=0.07, \Omega=0.2, d=0.8, D_a=0.8, \epsilon=0.2$



**Fig. 6h:** Stream function of  $D_a=\{0.65,0.8,0.95\}$  at  $Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \mu=0.07, \Omega=0.2, d=0.8, M_e=1.2, \epsilon=0.2$



**Fig. 6i:** Stream function of  $\epsilon=\{0.18,0.2,0.22\}$  at  $Q_0=Q_1=1.2, \phi=0.25, \rho=0.8, \mu=0.07, \Omega=0.2, d=0.8, M_e=1.2, D_a=0.8$

### 6. Conclusion Remarks

In this paper, we analyze the temperature and magnetohydrodynamic (MHD) peristaltic flow of a Sutterby fluid through a porous wavechannel under the effect of rotation. A summary of the above discussed results is as follows:

1. Increasing in the parameters  $Q_0 = Q_1$  and  $\epsilon$  leads to fluid's velocity increases. The velocity of fluid increases in the middle of the channel, but it decreases near the channel's walls when increases the parameters  $\phi, \Omega, d$  and  $D_a$ , while the fluid's velocity decreases in the middle of the channel, but it increases near the channel's walls when the parameters  $\mu$  and  $M_e$  increases.
2. Increasing in the parameters  $M_e$  and  $\mu$  leads to the pressure gradient rise, while by increasing the parameters  $\phi, \epsilon, d, \rho, \Omega$  and  $D_a$  leads to the pressure gradient  $dp/dx$  decreases.
3. Increasing in the parameters  $Q_0=Q_1, D_a, \rho, \phi, \epsilon$  and  $d$  leads to increase in the pressure rise, while by increasing the parameters  $\mu$  and  $M_e$  leads to decrease in the pressure rise.
4. Increasing in the parameters  $\mu$  and  $M_e$  leads to increase in the friction forces, while by increasing the parameters  $Q_0=Q_1, D_a, \rho, \phi, \epsilon$  and  $d$  leads to decrease in the friction forces.
5. Increasing in the parameters  $\rho, \Omega, d, D_a$  and  $E_c$  leads to increase in the temperature, while by increasing the parameters  $Q_0=Q_1, \mu, \epsilon, M_e$  and  $H_c$  leads to decrease in the temperature. By increasing the parameters  $\phi$  the temperature decreases at  $y < 0$ , while increases at  $y > 0$ . The temperature increases and decreases when the parameter  $P_a$  increases.

6. Increasing in the parameters  $Q_0=Q_1, \phi, \rho, \Omega, d, D_a$  and  $\epsilon$  leads to trapped bolus expanding, while an increase in the parameter  $\mu$  and the parameter  $M_e$  leads to trapped bolus shrinkage.

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