Global Estimates for Monotone Approximation

¹ Malik Saad Al-Muhja

Abstract. In 1995 Kopotun [3], introduced a paper approximation of k-monotone function. In this paper, we show that if f and g are k-monotone functions on [a,b], such that $f^{(\ell_j-1)}(x_j)=g^{(\ell_j-1)}(x_j)$ for all $0 \le j \le N$, then a direct theorem for the rate of k-monotone approximation in L_p -spaces of the k-th usual modulus of smoothness.

مبرهنات عامة في التقريب الرتيب

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الكلية الإسلامية الجامعة-قسم هندسة تقنيات الحاسبات 2010

المستخلص: في عام 1995م قدم الرياضي الكندي كبوتون [3] بحث في التقريب للدالة الرتيبة k. وفي هذا البحث بينا أذا كانت f,g دوال رتيبة من الدرجة k معرفة على الفترة [a,b] بحيث آن مشتقات هذه الدوال تكون متساوية عند نقاط الاندراج فان المبر هنة المباشرة تكون التقريب الرتيب k في الفضاءات L_p بدلالة مقياس النعومة m وان النتيجة لهذه المبر هنة تكون التقريب الرتيب m ولكن بدلالة مقياس النعومة m .

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1. Introduction.

In [5] Sammer, departure from these previous works is that you will prove simultaneous direct estimates for the rate of polynomial approximation in terms of the Ditzian-Totik modulus of smoothness. An other variant of her work in [5] is to consider the constrained and unconstrained problem of coapproximation and approximation of k-monotone and other functions in $L_p[-1,1]$, 0 .

Let $L_p[a,b]$, 0 , be the set of all measurable functions on <math>[a,b] such that $\|f\|_{L_p[a,b]} < \infty$, where

$$||f||_{L_p[a,b]} := \left(\int_a^b |f(x)|^p dx\right)^{\frac{1}{p}}.$$

Let us recall some definitions of moduli of smoothness used throughout this paper . The k th symmetric difference of f is given by:

$$\Delta_{h}^{k}(f, x, [a, b]) := \begin{cases} \sum_{i=0}^{k} {k \choose i} (-1)^{k-i} f\left(x - \frac{kh}{2} + ih\right) & x \pm \frac{kh}{2} \in [a, b], o < h < 1. \\ 0 & o.w. \end{cases}$$

The *k* th usual modulus of smoothness of $f \in L_p[a,b]$ is defined by :

$$\omega_k(f,\delta,[a,b])_p := \sup_{0 \le h \le \delta} \left\| \Delta_h^k(f,\cdot,[a,b]) \right\|_{L_p[a,b]}.$$

The Ditzian-Totik modulus of smoothness which is defined for such an f, as follows

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$$\omega_{k}^{\phi}(f,\delta,[a,b])_{p} \coloneqq \sup_{0 \le h \le \delta} \left\| \Delta_{h\phi(.)}^{k}(f,\cdot,[a,b]) \right\|_{L_{p}[a,b]}.$$

It will be omitted for the sake of simplicity,

$$\omega_k(f,[a,b])_P = \omega_k(f,\delta,[a,b])_P$$

For $f \in L_p[a,b]$, let

$$E_n(f)_p = \inf_{p_n \in \Pi_n} ||f - p_n||_p,$$

denote the *degree of unconstrained approximation*, where Π_n , the set of all polynomials of degree $\leq n$, and n is natural, i.e., $n \in \mathbb{N}$.

2. Notations and Definitions.

Let $\theta_N = \theta_N[a,b] = \{x_i\}_{i=0}^N = \{a = x_o \le ... \le x_{N-1} \le x_N = b\}$ be a partition of [a,b] into $\le N$, subintervals. We denote $\|\theta_N\| = \|\theta_N[a,b]\| = \max_{0 \le i \le N-1} \{x_{i+1} - x_i\}$, the length of the largest interval in that partition (the norm of the partition), and denote the length of the smallest interval by

$$\langle \theta_N \rangle = \langle \theta_N [a, b] \rangle = \min_{0 \le i \le N-1} \{ x_{i+1} - x_i \}$$
.

We call a partition $\theta_N[a,b]$, almost uniform if

$$\|\theta_N[a,b]\| \le 3\langle \theta_N[a,b]\rangle$$
,[4].

It was shown in [4], that any partition $\theta_N[a,b]$ of [a,b] can be made almost uniform by deleting some of the partition points: For any partition $\theta_N[a,b]$, there exists a superpartition $\tilde{\theta}_N[a,b]$ (i.e., partition $\tilde{\theta}$ is obtained from θ , by deleting some of the points of θ)

which is almost uniform and such that

$$\|\theta\| \le \langle \widetilde{\theta} \rangle \le \|\widetilde{\theta}\| \le 3\|\theta\|$$
.

In this result we obtain a relationship between two functions by using a partition θ_N .

3. The Main Result and Auxiliary Lemma.

Let us introduce the following auxiliary Lemma.

Lemma A. [2]

Let $k \ge 2$, and an interval $I \subset [a,b]$ be such that $b-a \le A.dist(I,\{a,b\})$, for some $A \in R$, and $\{t_1,...,t_{k-1}\}$ be a set of any k-1, points in I. If f,g in $\Delta^k[a,b] \cap L_p[a,b]$ are such that $f^{(\ell_j-1)}(t_j) = g^{(\ell_j-1)}(t_j)$, for all $0 \le j \le k$, (where $t_\circ = a$, $t_k = b$, and $\ell_j = \ell_j(\{t_i\}_{i=0}^k)$), then

$$||f-g||_p \le C \min\{\omega_k(f,[a,b])_p,\omega_k(g,[a,b])_p\},$$

where the constant C, depends only on k and A.

Theorem I.

Suppose that $N \ge k \ge 2$, and let $\theta_N = \theta_N[a,b] = \{a = x_0 \le ... \le x_{N-1} \le x_N = b\}$ be a

partition of [a,b] into $\leq N$, subintervals such that $\|\theta_N\| < \frac{b-a}{3(k-1)}$. Also, let f,g in $\Delta^k[a,b] \cap L_p[a,b]$ be such that $f^{(\ell_j-1)}(x_j) = g^{(\ell_j-1)}(x_j)$, $0 \leq j \leq N$. Then, $\|f-g\|_p \leq C \min\{\omega_k(f,\|\theta_N\|,[a,b])_p,\omega_k(g,\|\theta_N\|,[a,b])_p\}$, where the constant C, depends only on k.

Corollary II.

Suppose that $N \ge k \ge 2$, and let $\theta_N = \theta_N[a,b] = \{a = x_o \le ... \le x_{N-1} \le x_N = b\}$ be a partition of [a,b] into $\le N$, subintervals such that $\|\theta_N\| < \frac{b-a}{3(k-1)}$. Also, let f,g in $\Delta^k[a,b] \cap L_p[a,b]$ be such that $f^{(\ell_j-1)}(x_j) = g^{(\ell_j-1)}(x_j)$, $0 \le j \le N$. Then, $\|f-g\|_p \le C \min\{\omega_k^{\phi}(f,N^{-1},[a,b])_p,\omega_k^{\phi}(g,N^{-1},[a,b])_p\}$, where the constant C, depends only on k.

PROOF OF THEOREM I.

Without loss of generality, assume that

$$\omega_{k}(f, \|\theta_{N}\|, [a,b])_{p} \leq \omega_{k}(g, \|\theta_{N}\|, [a,b])_{p}.$$

An almost uniform partition of [a,b], $\tilde{\theta}$ is a superpartition of $\theta_N[a,b]$, such that

$$\|\theta_N\| \le \langle \widetilde{\theta} \rangle \le \|\widetilde{\theta}\| \le 3\|\theta_N\|$$
.

Since $\|\theta_N\| < \frac{b-a}{3(k-1)}$, this implies that $\|\widetilde{\theta}\| < \frac{b-a}{(k-1)}$, and therefore $\widetilde{\theta}$, consists of at least k intervals. Now, it is sufficient to prove (theorem I), for the partition $\widetilde{\theta}$, instead of θ_N .

Equivalently, we can assume that the original partition θ_N is almost uniform. Hence, we finish the proof of the theorem assuming that $\|\theta_N\| \le 3\langle \theta_N \rangle$, and that θ_N , consist of at least k intervals.

Let i, $0 \le i \le N-1$ be fixed , and denote $\alpha(i) = \max\{0, i-k+1\}$, and $J_i = \left[x_{\alpha(i)}, x_{\alpha(i)+k}\right]$. Since $\theta_N[a,b]$, consists of at least k intervals , then $\left[x_i, x_{i+1}\right] \subset J_i \subset [a,b]$. Taking into account that $|J_i| \approx \|\theta_N\|$, we can now apply theorem A, with $\left[a,b\right] = J_i$, $t_j = x_{\alpha(i)+j}$, $0 \le j \le k$, and $I = \left[t_1, t_{k-1}\right]$, to conclude that

$$\begin{split} \left\| f - g \right\|_{L_{p}\left[x_{i}, x_{i+1}\right]} &\leq \left\| f - g \right\|_{L_{p}\left(J_{i}\right)} \\ &\leq C \omega_{k} \left(f, J_{i} \right)_{p} \\ &\leq C \omega_{k} \left(f, \left\| \theta_{N} \right\|, \left[a, b \right] \right)_{p}, \end{split}$$

where C, depends only on k, because we can choose a constant A, in the statement of theorem A, to be 3k, since

$$\frac{|J_i|}{dist(I, \{x_{\alpha(i)}, x_{\alpha(i)+k}\})} \le \frac{k \|\theta_N\|}{\langle \theta_N \rangle} \le 3k \cdot [4]$$

We get

$$|J_i| \le 3k \operatorname{dist}(I, \{x_{\alpha(i)}, x_{\alpha(i)+k}\}).$$

Since *there exists* i, $0 \le i \le N-1$, such that $||f-g||_{L_p[a,b]} = ||f-g||_{L_p[x_i,x_{i+1}]}$, then

$$||f - g||_{L_P[a,b]} \le C\omega_k (f, ||\theta_N||, [a,b])_P$$
.

PROOF OF COROLLARY II.

Let
$$[a,b] \subseteq [-1,1]$$
 be $\theta_N[a,b] = \{x_i\}_{i=0}^N$, a partition and $C_2^{-1} \|\theta_N\| \le \langle \theta_N \rangle \le C_2 \|\theta_N\|$. (1)

Since,

$$||f - g||_{P} \le C \min \{ \omega_{k} (f, ||\theta_{N}||, [a, b])_{P}, \omega_{k} (g, ||\theta_{N}||, [a, b])_{P} \}.$$

Then from (1), and Lemma 2.2.5 in [5], if we assume $\langle \theta_N \rangle = \frac{c}{N}$, c > 0, we get $||f - g||_P \le C \min \{ \omega_k^{\phi} (f, N^{-1}, [a, b])_P, \omega_k^{\phi} (g, N^{-1}, [a, b])_P \}$.

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