

An efficient Approximate Solution for Non-Linear Solar Cell Equation using Inverse Quadratic Interpolation Method

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ARTICLE INFO

Article history:

Received: 28 /10/2020
 Revised form: 29 /12/2020
 Accepted : 31 /12/2020
 Available online: 02 /01/2021

Keywords:

Inverse Quadratic Interpolation method; iterative method; Newton's algorithm; non-linear equation.

ABSTRACT

The main purpose of this research is to discuss the numerical solutions of a single-diode nonlinear equation for a solar cell in a more efficient way. The inverse quadratic interpolation technique for finding the root(s) of a function is applied to our study problem. Numerical results show that the proposed three points iterative method is compatible to Newton's method, accurate and effective.

MSC. 41A25; 41A35; 41A36.

DOI : <https://doi.org/10.29304/jqcm.2020.12.4.723>

1. Introduction

Many problems require finding some or all roots of a non-linear equation. In general, an equation containing one variable can be written as $f(x) = 0$. There are a number of numerical methods to find an approximate value for a given root of the previous equation, the numerical iterative algorithms for example iterative, regular false; Bisection; secant and Newton techniques are used to achieve the approximate numerical solution of these equations [1-5]. All these numerical methods need a rough approximate value of a given equation root to enable it to generate sequential initial values of a given equation root to enable it to generate a sequential of better approximate values for that root. There are many techniques improved on the perfection of convergent Newton's method, in order to obtain a superior convergence order than NRM [6-11].

This paper is attention with the iterative algorithm to get the voltage's value of the photovoltaic cell V_{pv} in the conditions $f(x) = 0$, and $f'(x) \neq 0$ where $f: \mathbb{R} \rightarrow \mathbb{R}$ be real function. It is systematic as the following steps: section two describes the design of the model chosen (Equation of Non-linear Solar Cell); section three characterizes the two

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Communicated by: Alaa Hussein Hamadi

numerical formulas; the proposed method (Inverse Quadratic Interpolation method) have been portrayed; section four results and discussion; finally section five the checked results have been concluded.

2. Equation of Non-linear Solar Cell

The current and voltage characteristics of the solar cell can be illustrated by the following equations [12-16]

$$I_{source} = I_{ph} \tag{1}$$

$$I_D = I_s \times e^{(V_D/nV_T)} - 1 \tag{2}$$

Merge Eq. 1 in Eq. 2, yields

$$I_{source} - I_s(e^{(-V \times q/m \times k \times T)} - 1) = V/R \tag{3}$$

In Ohms law; Current = $\frac{\text{Voltage}}{\text{Resistance}}$, Power = Current \times Voltage

Then $I_{pv} = V_{pv}/R$; $P_{pv} = I_{pv} \times V_{pv}$ [20-21] (4)

where:

I_s : The reverse saturation current= 10^{-12} measured in Ampere; I_{ph} : The photocurrent measured in Ampere; I_0 : The reverse saturation current of the diode measured in Ampere; I_{pv} and V_{pv} are the delivered current and voltage measured in Ampere and Volt respectively; $KT/q = 0.026 \text{ V} = 26 \text{ mV}$ at room Temperature ($T = 25 \text{ }^\circ\text{C}$); m : The recombination factor = 1.2; The electron charge $q = 1.6 \times 10^{-19} \text{ C}$, The Boltzmann constant $k = 1.38 \times 10^{-23} \text{ J/K}$ [20-21].

3. Numerical Formulas

Definition 3.1 The Newton's method so called Newton Raphson method, is a root- finding algorithm that uses the first few terms of the Taylor series of a function $f(x)$ approximately a suspected root The algorithm is applied iteratively to obtain [17]

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)} \text{ for } n = 0, 1, 2, \dots \tag{5}$$

Definition 3.2 The Inverse quadratic interpolation is a root-finding algorithm, for solving equations of the form $y = f(x) = 0$. The idea is to use quadratic interpolation to approximate the inverse of f . IQIM required three initial values x_0, x_1, x_2 and realized by the recurrence relation

$$x_{n+1} = \frac{f_{n-1}f_n}{(f_{n-2}-f_{n-1})(f_{n-2}-f_n)} x_{n-2} + \frac{f_{n-2}f_n}{(f_{n-1}-f_{n-2})(f_{n-1}-f_n)} x_{n-1} + \frac{f_{n-2}f_{n-1}}{(f_n-f_{n-2})(f_n-f_{n-1})} x_n \tag{6}$$

where $f_n = f(x_n)$

4. Results and Discussion

Consider the Eq. 3, the initial value $x_0 = 1$; the results obtained by IQIM method are shown in Tables 1, 2, 3, 4 and 5 with using load resistance $R = 1, 2, 3, 4$ and 5. By supposing that $\epsilon = 10^{-9}$ as the tolerance.

$$\sigma = |x_{n+1} - x_n| < \epsilon, |f(x_n)| < \epsilon$$

Tables 1 to 5 show the results for the proposed method when the load resistance $R = 1$; and Figure 1, 2, 3, 4 and 5 present the acquired results using the standard and proposed methods.

Table 1 - The roots of Eq. 3 using Inverse quadratic interpolation (R = 1).

The load resistance $R = 1$				
Iterations	V_{pv} -IQIM	I_{pv} -IQIM	P_{pv} -IQIM	ϵ - IQIM
1	0.933205006	0.933205006	0.870871583	0.010781872
2	0.92406215	0.92406215	0.853890857	0.001639015
3	0.922462853	0.922462853	0.850937715	3.971810E-05
4	0.922423156	0.922423156	0.850864479	2.164130E-08
5	0.922423135	0.922423135	0.850864439	5.884180E-15
6	0.922423135	0.922423135	0.850864439	0.000000000

Table 2 - The roots of Eq. 3 using Inverse quadratic interpolation (R = 2).

The load resistance $R = 2$				
Iterations	V_{pv} -IQIM	I_{pv} -IQIM	P_{pv} -IQIM	ϵ - IQIM
1	0.930694821	0.46534741	0.433096425	0.013659438
2	0.919616307	0.459808154	0.422847076	0.002580925
3	0.917134941	0.458567471	0.42056825	9.955880E-05
4	0.917035522	0.458517761	0.420477074	1.396400E-07
5	0.917035382	0.458517691	0.420476946	2.496890E-13
6	0.917035382	0.458517691	0.420476946	0.000000000

Table 3 - The roots of Eq. 3 using Inverse quadratic interpolation (R = 3).

The load resistance $R = 3$				
Iterations	V_{pv} -IQIM	I_{pv} -IQIM	P_{pv} -IQIM	ϵ - IQIM
1	0.92805625	0.309352083	0.287096134	0.017652876
2	0.914591297	0.304863766	0.278825747	0.004187923
3	0.910667481	0.303555827	0.27643842	0.000264107
4	0.910404391	0.30346813	0.276278718	1.017030E-06
5	0.910403374	0.303467791	0.276278101	1.362810E-11
6	0.910403374	0.303467791	0.276278101	0.00000000

Table 4 - The roots of Eq. 3 using Inverse quadratic interpolation (R = 4).

The load resistance $R = 4$				
Iterations	V_{pv} -IQIM	I_{pv} -IQIM	P_{pv} -IQIM	ϵ - IQIM
1	0.925280086	0.231320021	0.214035809	0.023539484
2	0.908858052	0.227214513	0.20650574	0.00711745
3	0.902502556	0.225625639	0.203627716	0.000761954
4	0.90174946	0.225437365	0.203288022	8.858440E-06
5	0.901740603	0.225435151	0.203284029	1.085660E-09
6	0.901740602	0.22543515	0.203284028	1.110220E-16
7	0.901740602	0.22543515	0.203284028	0.000000000

Table 5 - The roots of Eq. 3 using Inverse quadratic interpolation (R = 5).

The load resistance $R = 5$				
Iterations	V_{pv} -IQIM	I_{pv} -IQIM	P_{pv} -IQIM	ϵ - IQIM
1	0.922356344	0.184471269	0.170148245	0.03326363
2	0.902249489	0.180449898	0.162810828	0.013156774
3	0.891632149	0.17832643	0.159001578	0.002539434
4	0.88919712	0.177839424	0.158134304	0.000104405
5	0.889092881	0.177818576	0.15809723	1.659580E ⁻⁰⁷
6	0.889092715	0.177818543	0.158097171	3.731460E ⁻¹³
7	0.889092715	0.177818543	0.158097171	0.000000000

The material below gives the solution of Eq. 3 along with the estimated points solved in MATLAB. The results are found using Newton method. The some discussion on possible improvements. Our allowed tolerance was $\epsilon = 10^{-9}$.

1) Solutions of Eq. 3 with $R = 1$,

Estimated point for V_{pv} , at a point V: 0.922423135

Estimated point for I_{pv} , at a point I: 0.9224231350

Estimated point for P_{pv} , at a point P: 0.850864439

with number of iteration = 9.

2) Solutions of Eq. 3 with $R = 2$,

Estimated point for V_{pv} , at a point V: 0.917035382

Estimated point for I_{pv} , at a point I: 0.458517691

Estimated point for P_{pv} , at a point P: 0.420476946

with number of iteration $n = 9$.

3) Solutions of Eq. 3 with $R = 3$,

Estimated point for V_{pv} , at a point V: 0.910403374

Estimated point for I_{pv} , at a point I: 0.303467791

Estimated point for P_{pv} , at a point P: 0.276278101

with number of iteration $n = 9$.

4) Solutions of Eq. 3 with $R = 4$,

Estimated point for V_{pv} , at a point V: 0.901740602

Estimated point for I_{pv} , at a point I: 0.225435150

Estimated point for P_{pv} , at a point P: 0.203284028

with number of iteration $n = 9$.

5) Solutions of Eq. 3 with $R = 5$,

Estimated point for V_{pv} , at a point V: 0.889092715

Estimated point for I_{pv} , at a point I: 0.1778185430

Estimated point for P_{pv} , at a point P: 0.158097171

with number of iteration $n = 10$.

It would be expected that the IQIM could be as good as or possibly better than the newton method for $R = 1, 2, 3, 4$ and 5. This is an interesting case because we are only using transcendental function

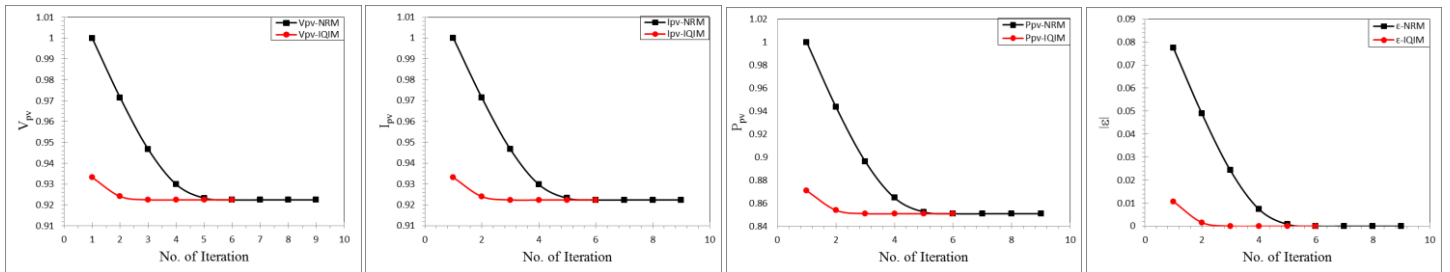


Fig. 1 - The absolute error and numerical results based on Eqs. 5 and 6.

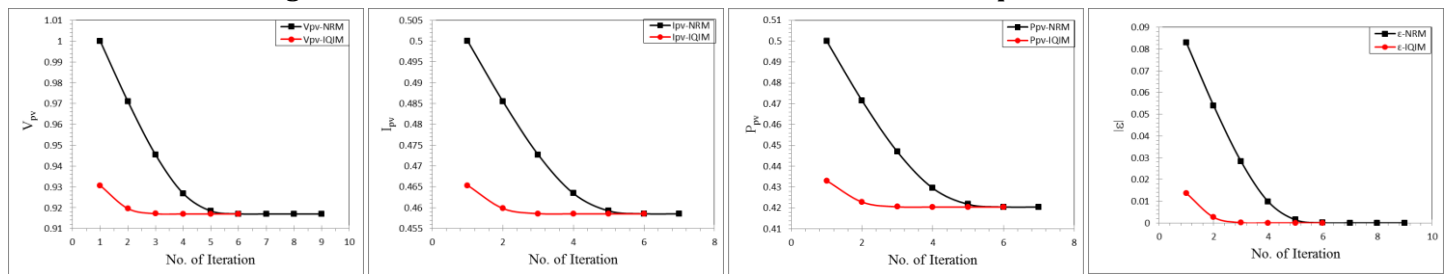


Fig. 2 - The absolute error and numerical results based on Eqs. 5 and 6.

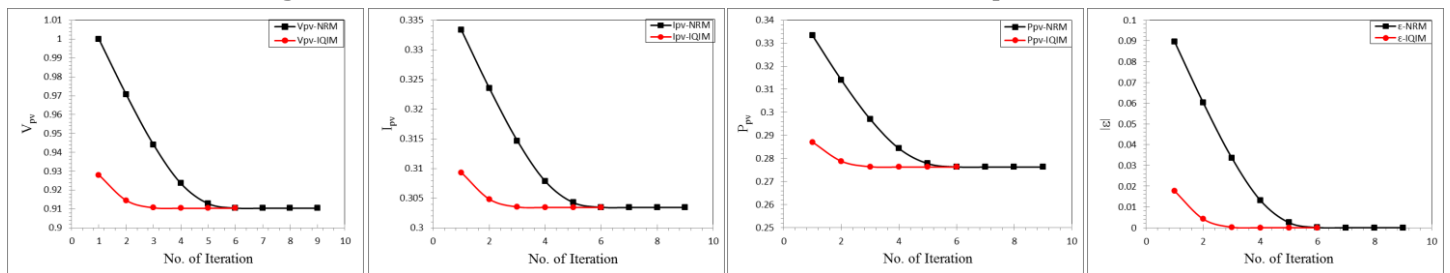


Fig. 3 - The absolute error and numerical results based on Eqs. 5 and 6.

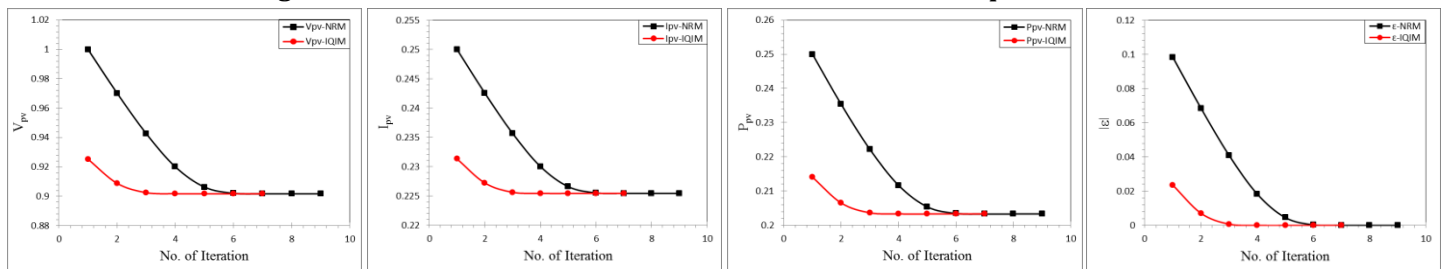


Fig. 4 - The absolute error and numerical results based on Eqs. 5 and 6.

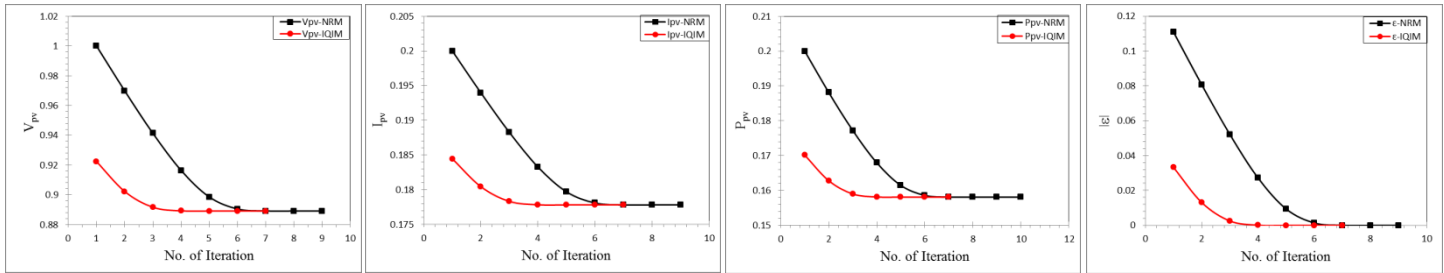


Fig. 5 - The absolute error and numerical results based on Eqns. 5 and 6.

5. Conclusion

We present the results of single-diode non-linear equation numerical tests to compare the efficiencies of the proposed technique. We used IQIM and Newton's techniques for solving non-linear equation of a solar cell. Numerical computations are reported in this paper.

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